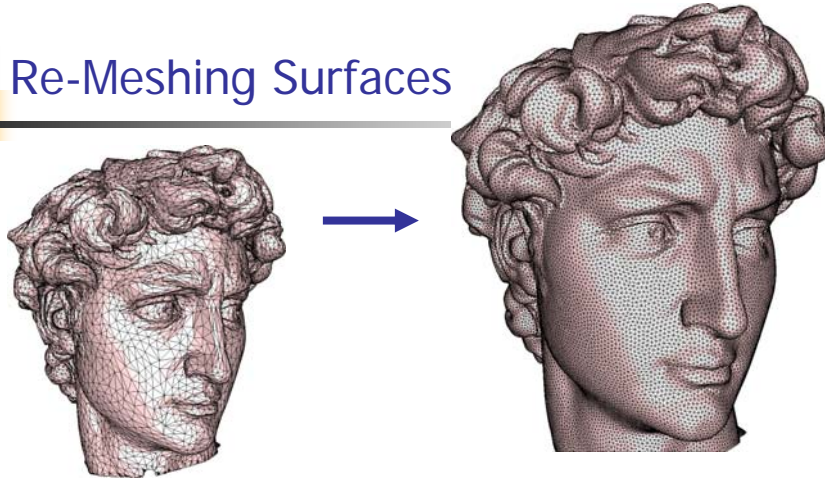




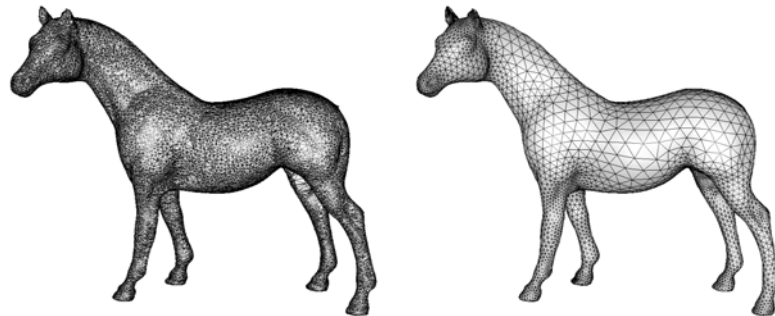
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## Re-Meshing Surfaces



## Re-Meshing Surfaces

- Given input mesh generate new mesh which is "better"
  - Element sizing
  - Element shape
- BUT is near (geometrically) to original surface



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## Hausdorff Metric

- Given two sets (surfaces) P and Q

$$H_P(Q) = \max_p \min_q \|p, q\|$$
$$H(P, Q) = \max(H_Q(P), H_P(Q))$$

- point to point
- On mesh approximate by
  - measuring vertex to surface distance
  - measuring vertex to vertex distance
- Expensive to compute
  - Public Domain Code: Metro

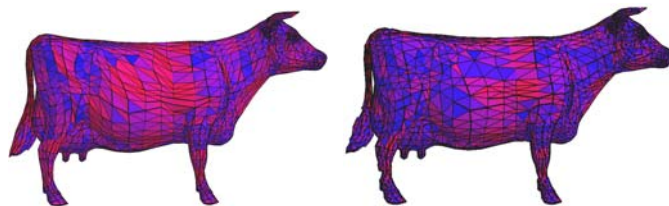


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## How to (re)mesh surfaces?

- Can we apply Delaunay triangulation?
  - What is Delaunay criterion on surface?
    - Option 1: Use sphere instead of circle
      - Works for volumetric meshes (tets)
    - Option 2: Use pairwise test only
      - Theoretical Delaunay properties do not hold
  - Boundary recovery = Approximation quality



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## Approaches

- Mesh adaptation/Local Remeshing
  - Modify existing mesh using sequence of local operations
    - Evaluate approximation quality at every step
- Reduction to 2D/Global Remeshing
  - Segment surface into parameterizable pieces
  - Parameterize in 2D
  - Mesh in 2D (Delaunay)
  - Project back

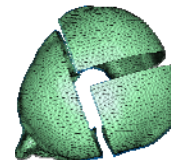
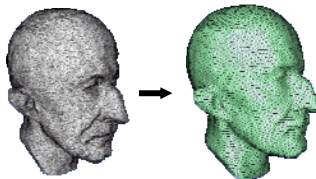
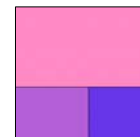
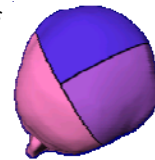


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## Reduction to 2D/Global Remeshing

- Segment surface into parameterizable charts
  - distortion/chart size (count) trade-off
- Parameterize in 2D
  - Distortion affects 3D mesh quality
- Mesh charts in 2D (Delaunay)
  - Take parametric distortion into account (sizing)
  - Take care of shared boundaries
- Project back

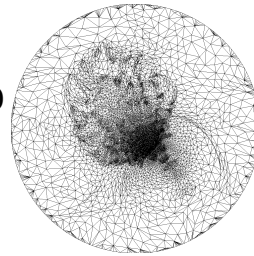
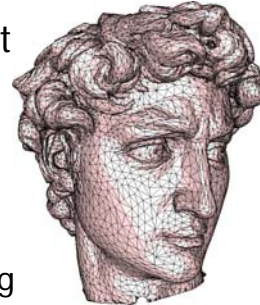


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## Parameterization

- Projection to/from 2D should not distort mesh
- Can handle some stretch
  - Measure & take into account during 2D meshing
    - Use as component of local sizing
- MUST be conformal
  - If care about quality
  - Want: Equilater (Delaunay) in 2D = equilateral (Delaunay) in 3D



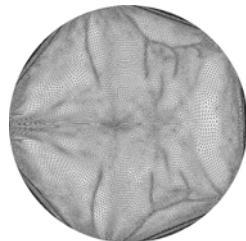
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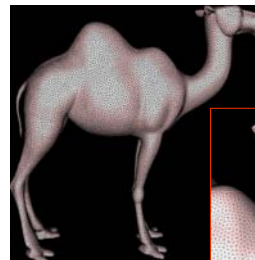
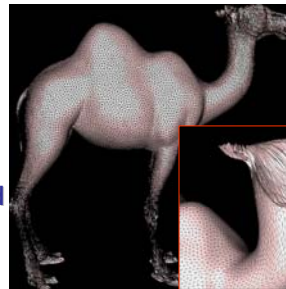
## Impact of distortion



tail



head



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## Segmentation

- Chart Properties
  - parameterizable: open + genus 0
  - Low distortion
    - Ideal: Developable charts
- Approaches
  - Single chart
    - Generate (short) cuts to reduce genus
    - Cut through high curvature/distortion vertices
  - Multiple charts
    - More convex boundaries – easier to handle

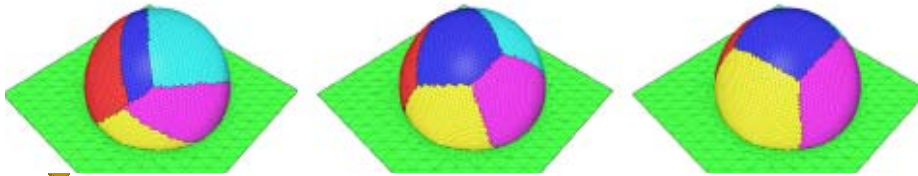


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## Lloyd Segmentation Framework

- Lloyd iterations:
  - Select random triangles to act as seeds
  - Grow charts around seeds using a greedy approach
  - Find new seed for each chart
    - Typically chart center
  - Repeat from step 2 until convergence



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## Proxies

- Charts represented by proxies – used for reseeding and growth
- Example I: Planar charts
  - Proxy: Normal to plane  $N_c$
  - Compute: Average normal of chart triangles
  - Growth metric: Normal difference  $F(C,t) = N_c \cdot n_t$

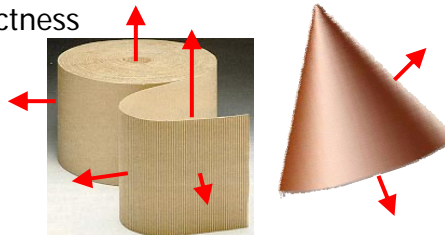
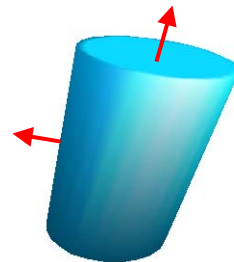


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## Example II: D-Charts (Devlopable Charts)

- Constant angle between surface normal and axis  
→ Developable chart
- Proxy:  $\langle \text{axis, angle} \rangle \quad \langle N_c, \theta_c \rangle$
- Compute:
 
$$\min_{N_c, \theta_c} \frac{1}{A_c} \sum_{t \in C} A_t F(C,t) \text{ s.t. } \|N_c\|=1$$
- Growth metric:
 
$$F(C,t) = (N_c \cdot n_t - \cos \theta_c)^2$$
  - Combine with compactness



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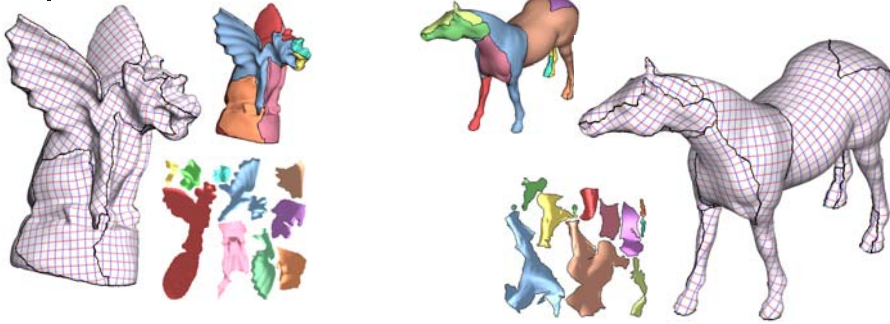
## Examples



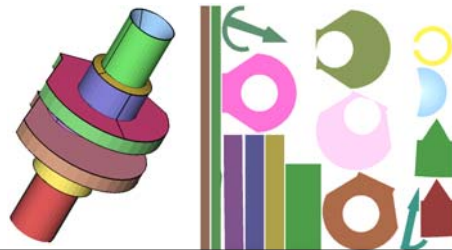
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## Example Results



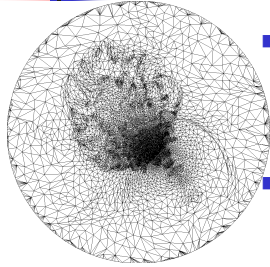
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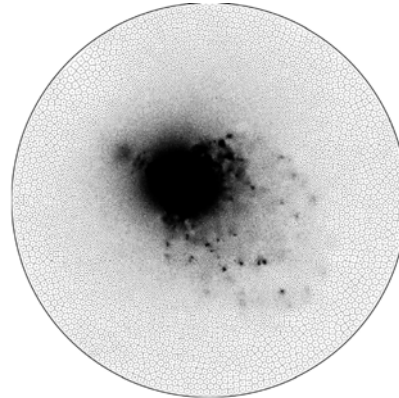
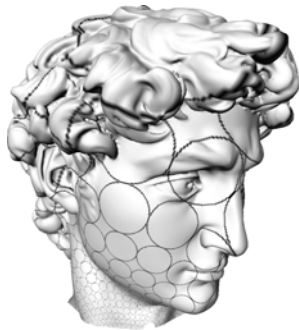




## Meshing - sizing



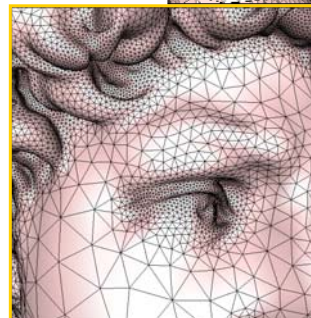
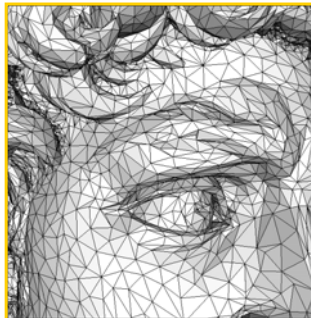
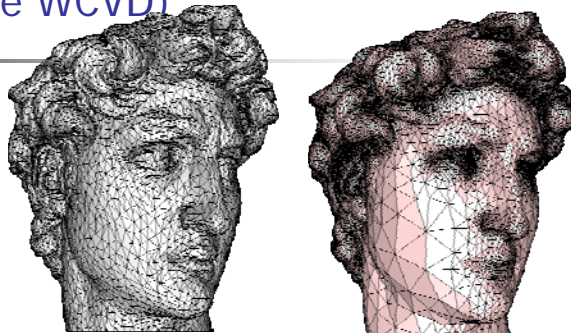
- Measure parametric stretch (3D to 2D)
  - Measure stretch per edge  $\|e_{3D}\|/\|e_{2D}\|$
  - Vertex stretch = average of edges
- Multiply sizing function (at vertices) by stretch



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## Example (use WCVD)



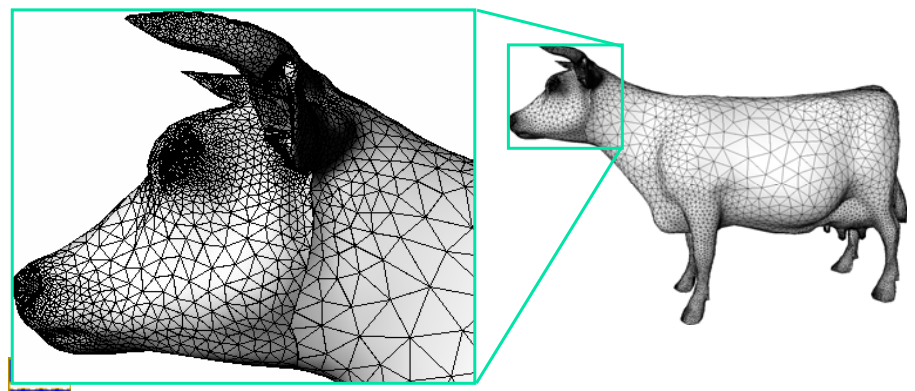
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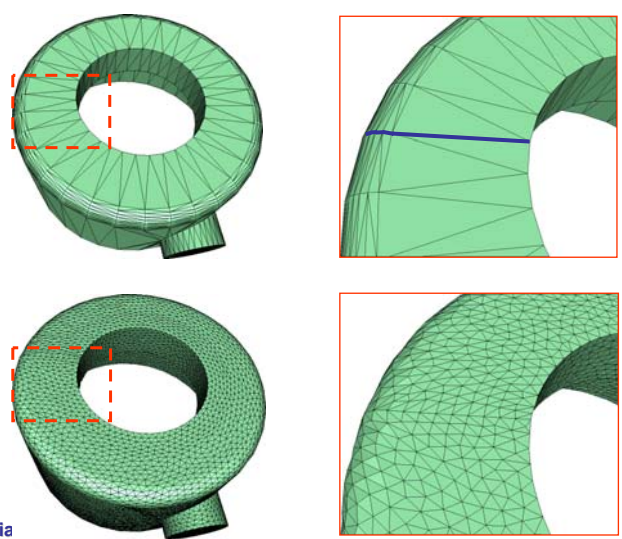
## Boundary

- Need mesh consistency along boundaries
- Enforce shared boundary vertex positions



## Boundaries

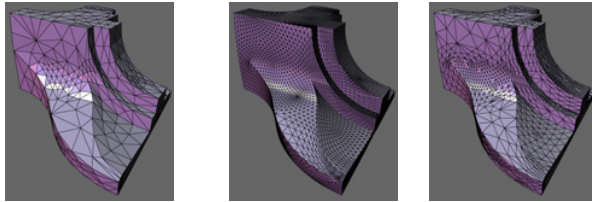
- Consistent but visible...





## Features

- Preserving features – locate surface creases and prevent removing them
  - Special handling by segmentation and/or 2D meshing



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## Global Methods - Properties

- Three major components:
  - Segment
  - Parameterize
  - Mesh in 2D
- Strongly depends on parameterization quality
  - In turn depends on segmentation
- More “formal”
- Typically more complex to implement from scratch



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