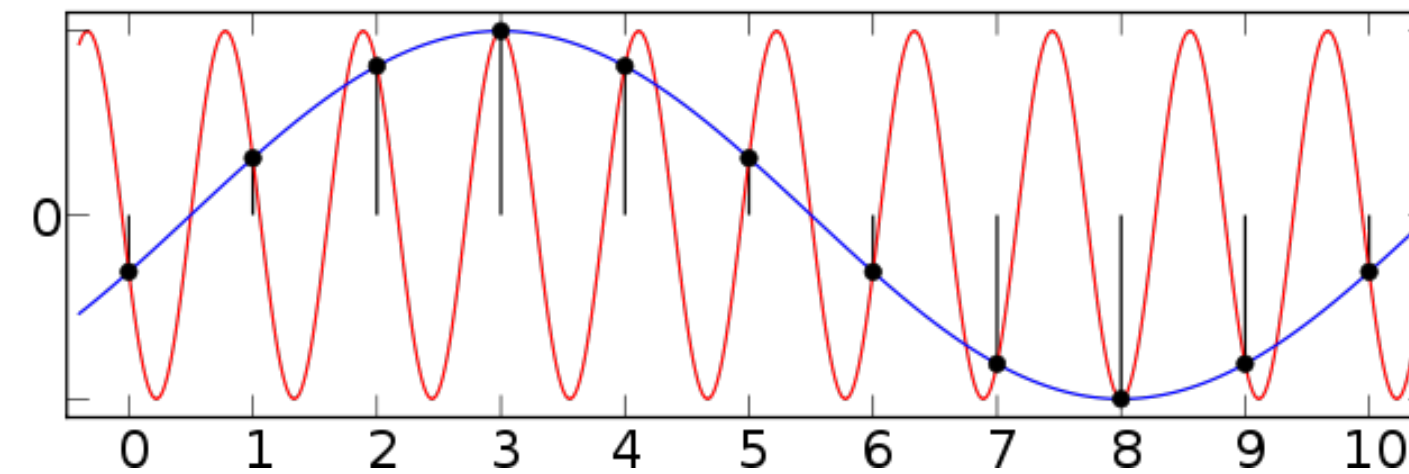


# CPSC 425: Computer Vision



**Image Credit:** [https://en.wikibooks.org/wiki/Analog\\_and\\_Digital\\_Conversion/Nyquist\\_Sampling\\_Rate](https://en.wikibooks.org/wiki/Analog_and_Digital_Conversion/Nyquist_Sampling_Rate)

## Lecture 6: Sampling

( unless otherwise stated slides are taken or adopted from **Bob Woodham, Jim Little** and **Fred Tung** )

# Menu for Today

## Topics:

- **Sampling** theory
- **Nyquist** rate
- Color **Filter Arrays**
- **Image** encoding

## Readings:

- **Today's** Lecture: Szeliski 2.3, Forsyth & Ponce (2nd ed.) 4.5, 4.6

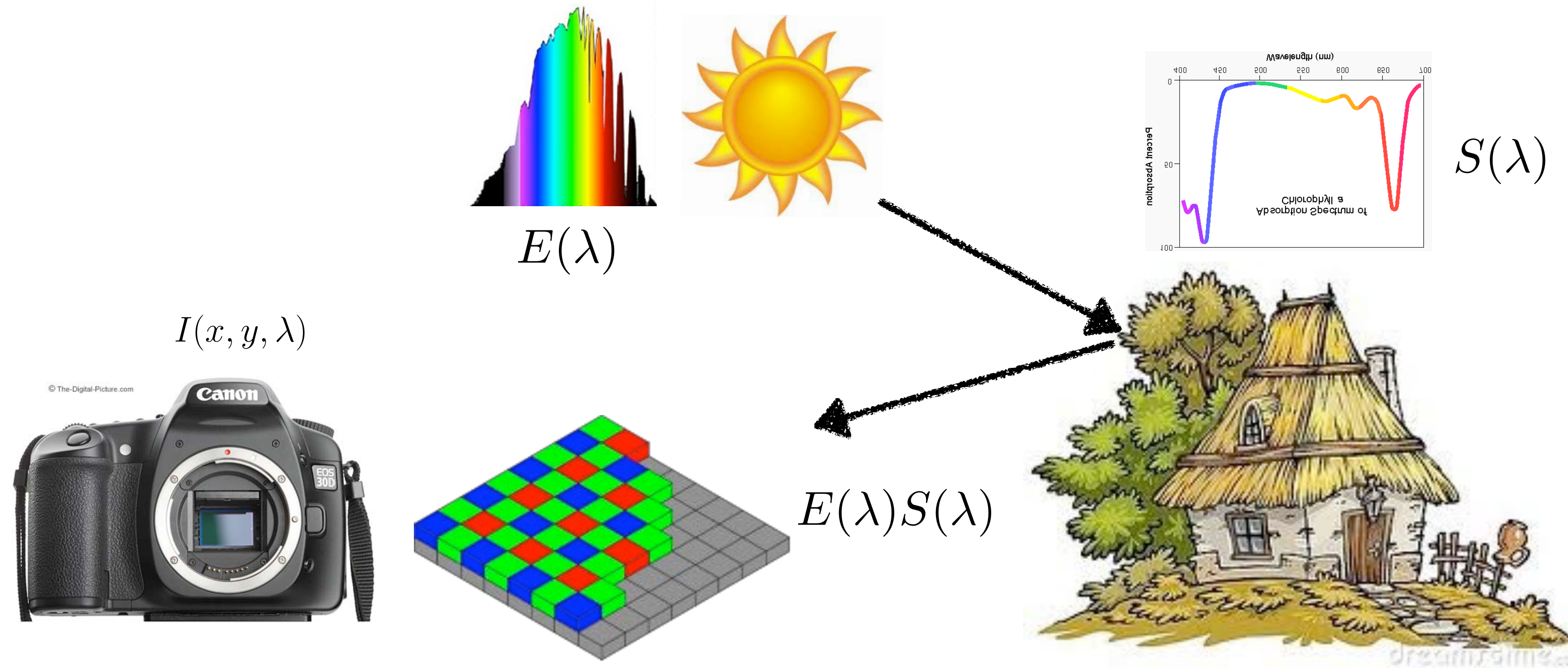
## Reminders:

- **Assignment 1:** Image Filtering and Hybrid Images due **September 28th**

# Goal

1. Understand discrete  $\neq$  continuous
2. How do we then deal with this?

# What is **Sampling**?



A **continuous function**  $I(x, y, \lambda)$  is presented at the image sensor at each time instant

How do we convert this to a **digital signal** (array of numbers)?

How can we **manipulate**, e.g., resample, this digital signal correctly?

# Resampling Images

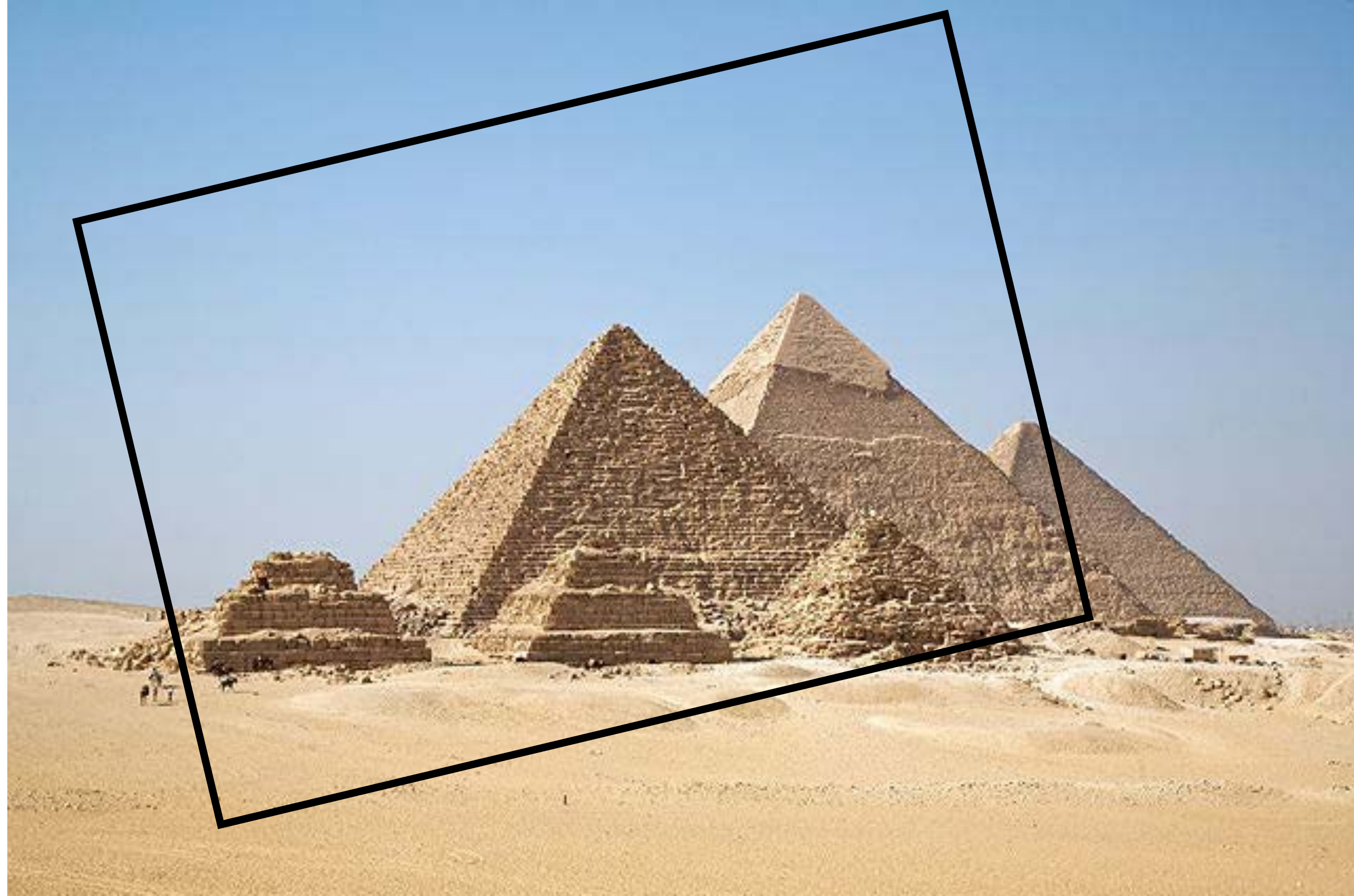
width



height

# Resampling Images

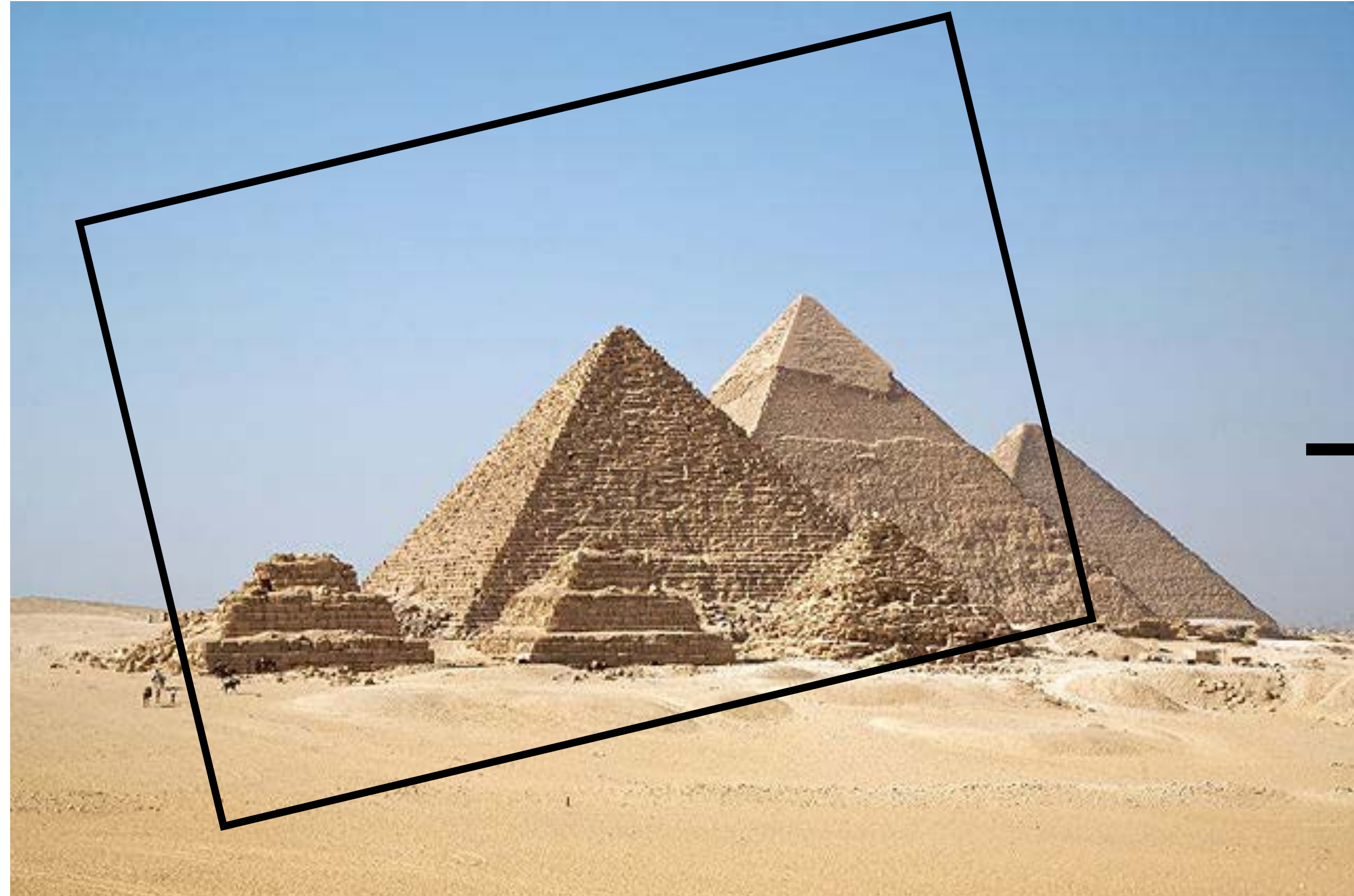
width



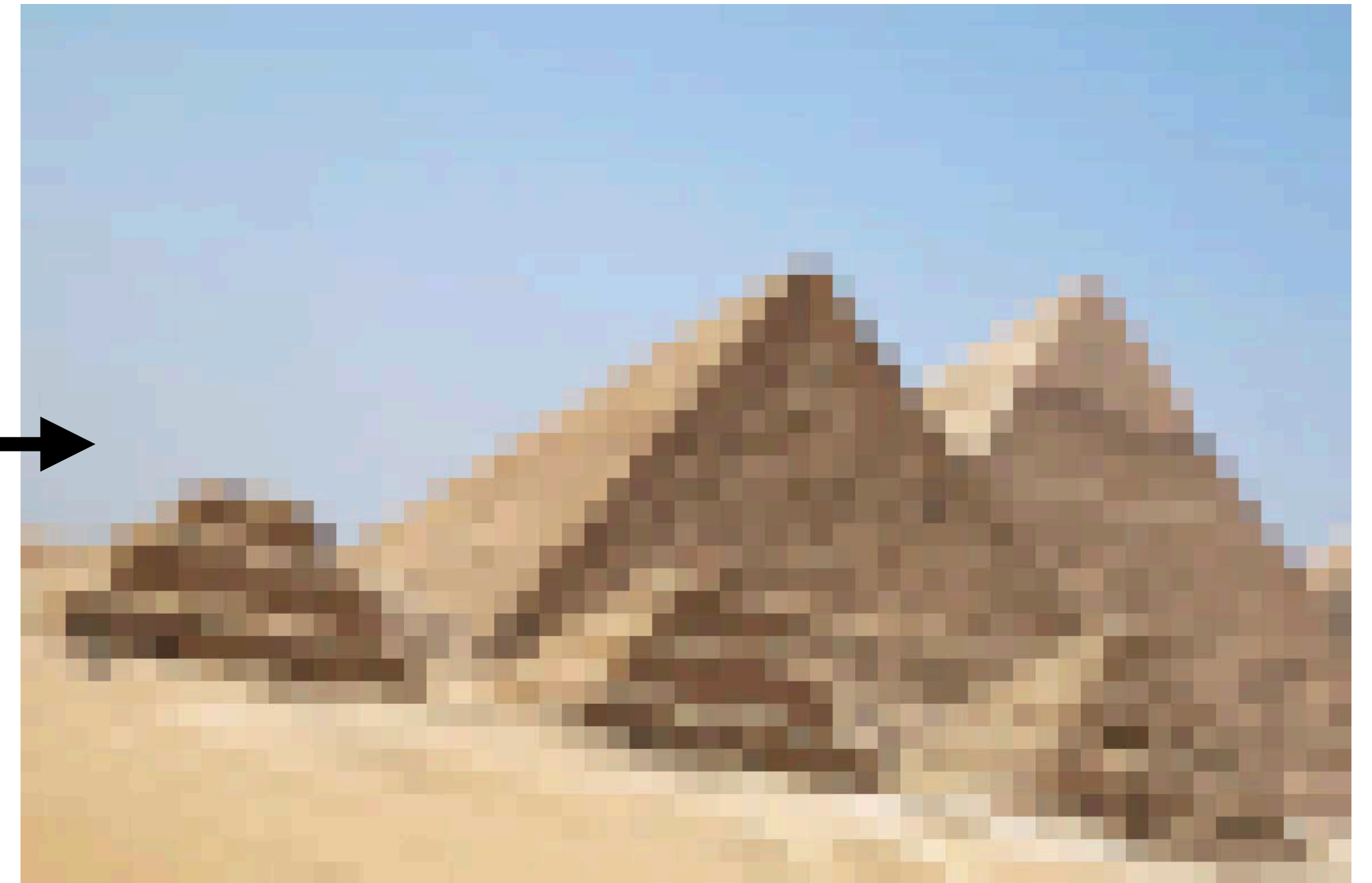
height

# Resampling Images

width



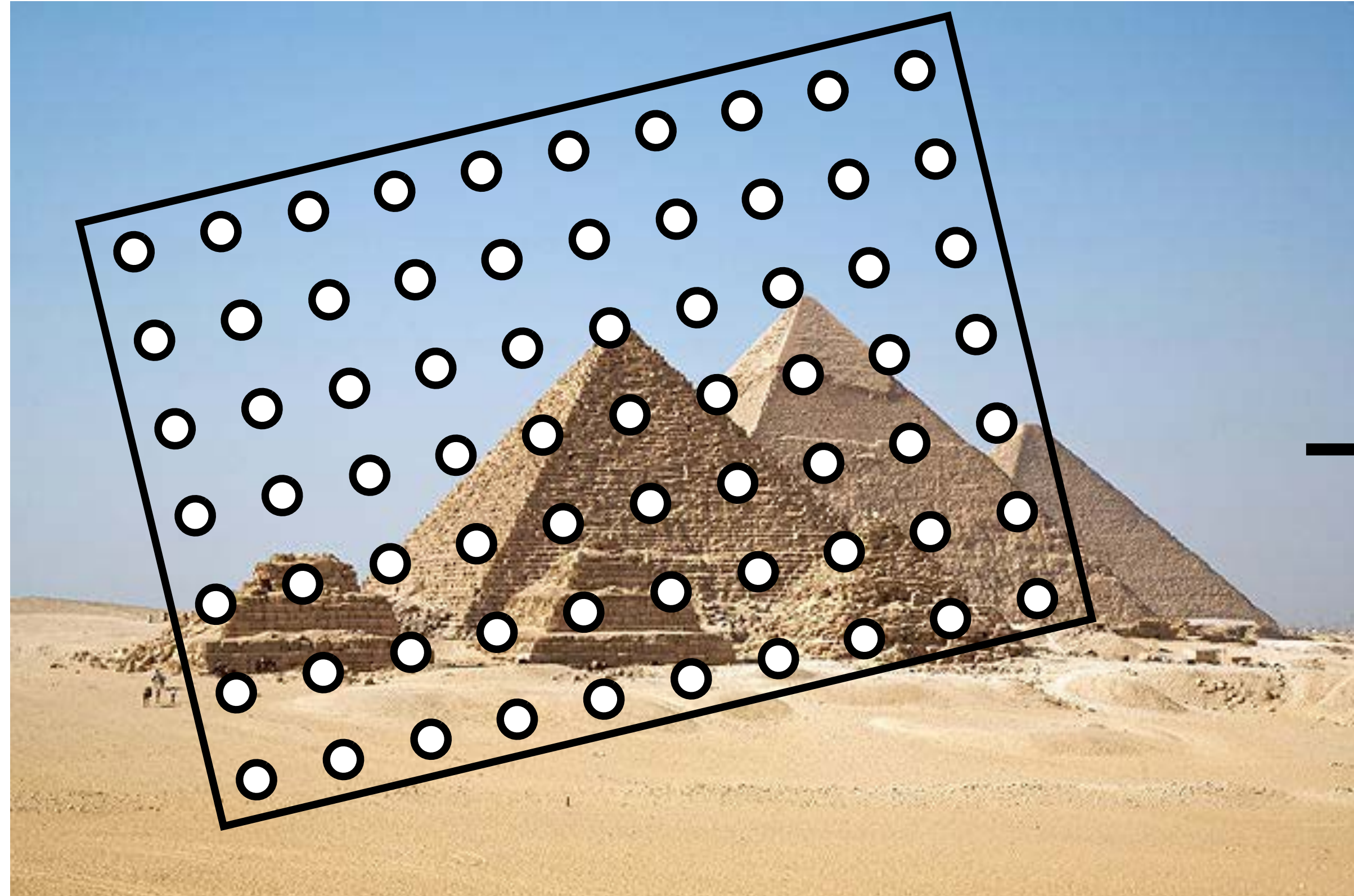
10



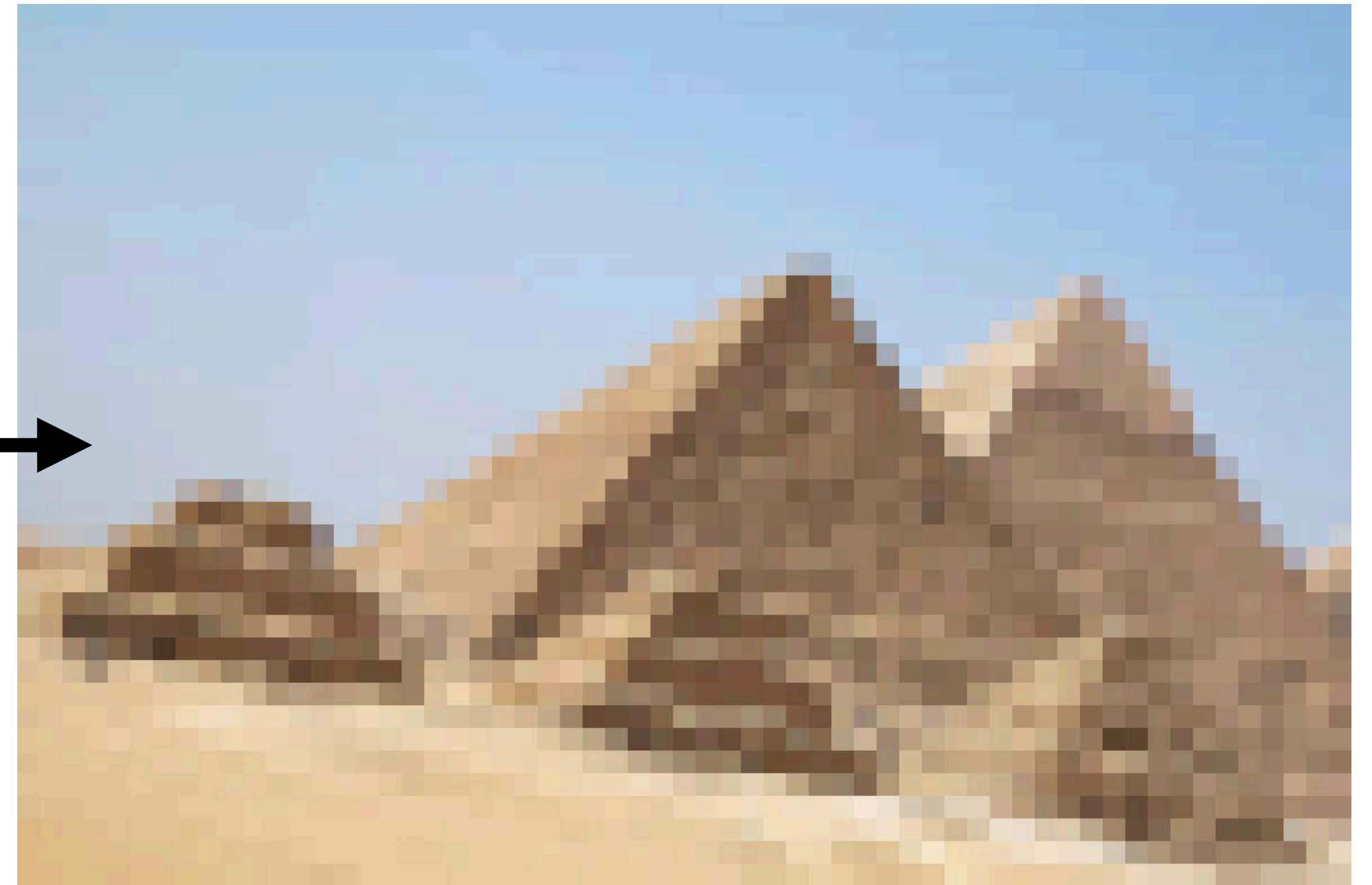
7

# Resampling Images

width



10



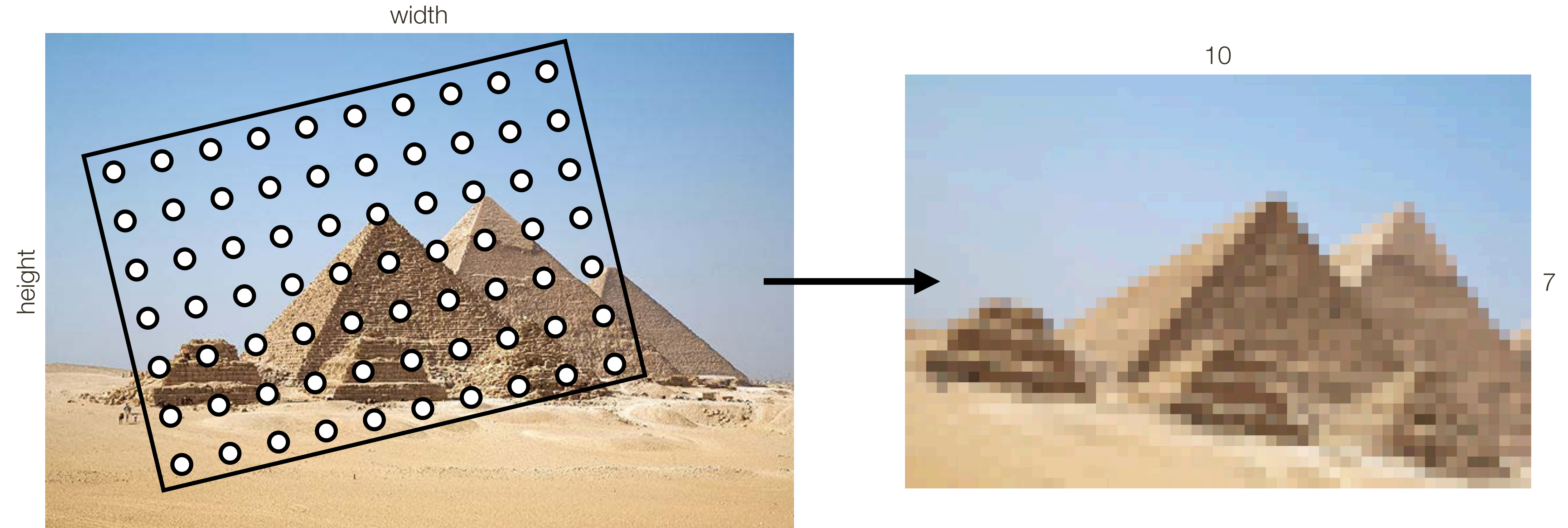
7



height



# Resampling Images



How do we correctly **generate samples** to resample or warp an image?

# What types of **transformations** can we do?

$I(X, Y)$



**Filtering**



$I'(X, Y)$



changes range of image function

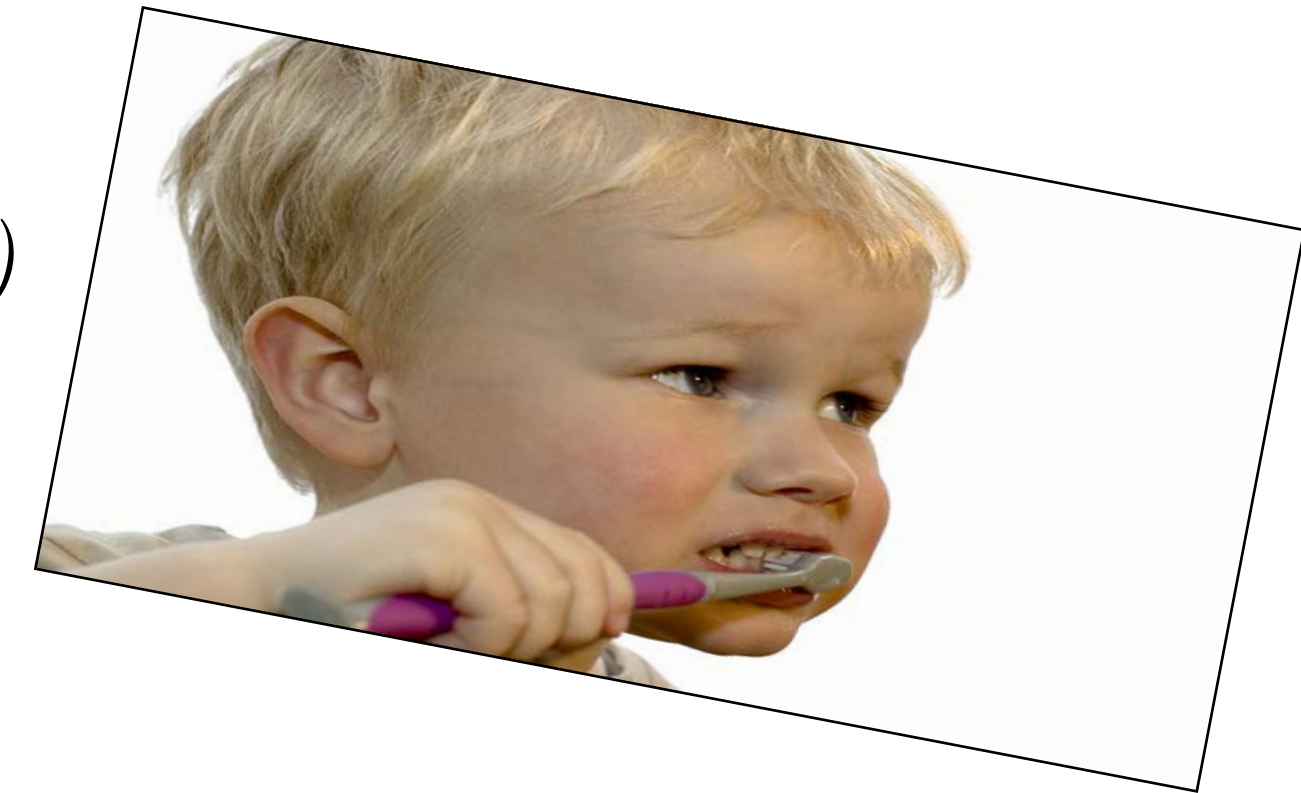
$I(X, Y)$



**Warping**



$I'(X, Y)$



changes domain of image function

# What types of **transformations** can we do?

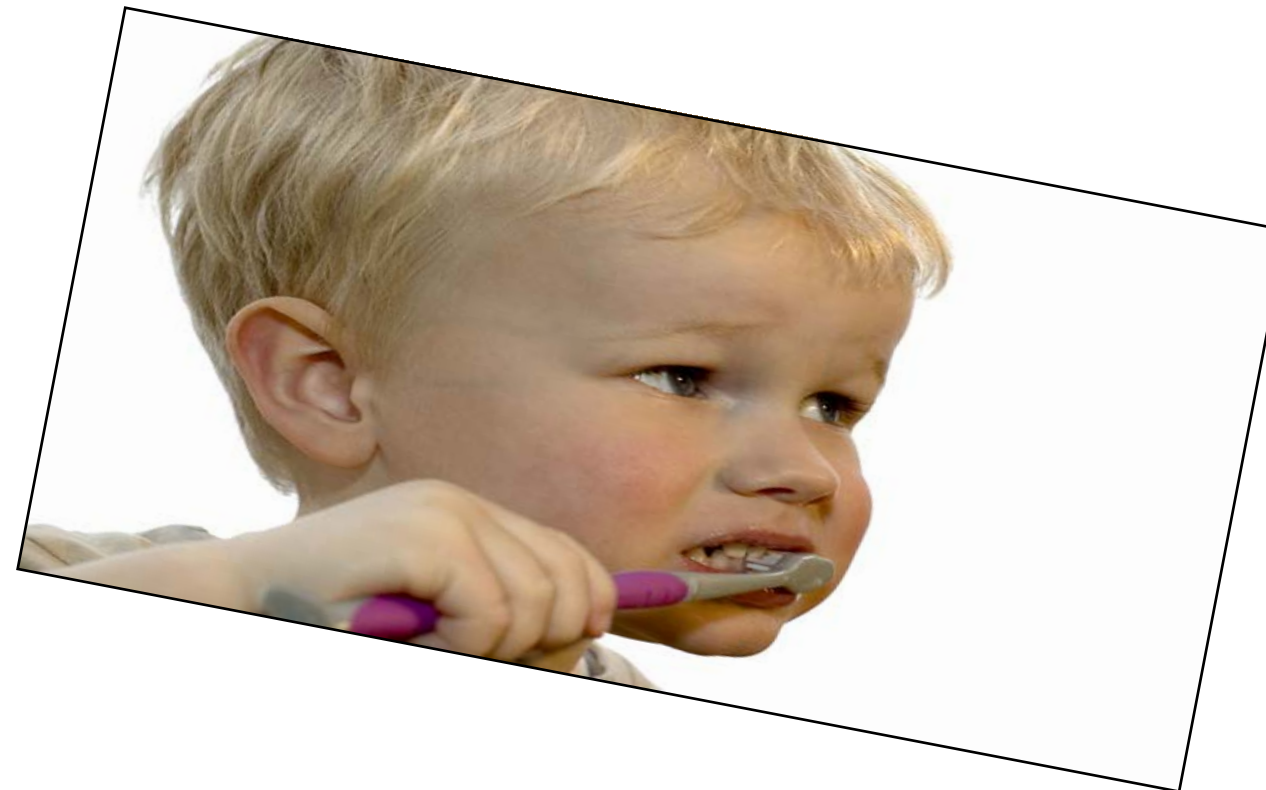
$I(X, Y)$



**Warping**



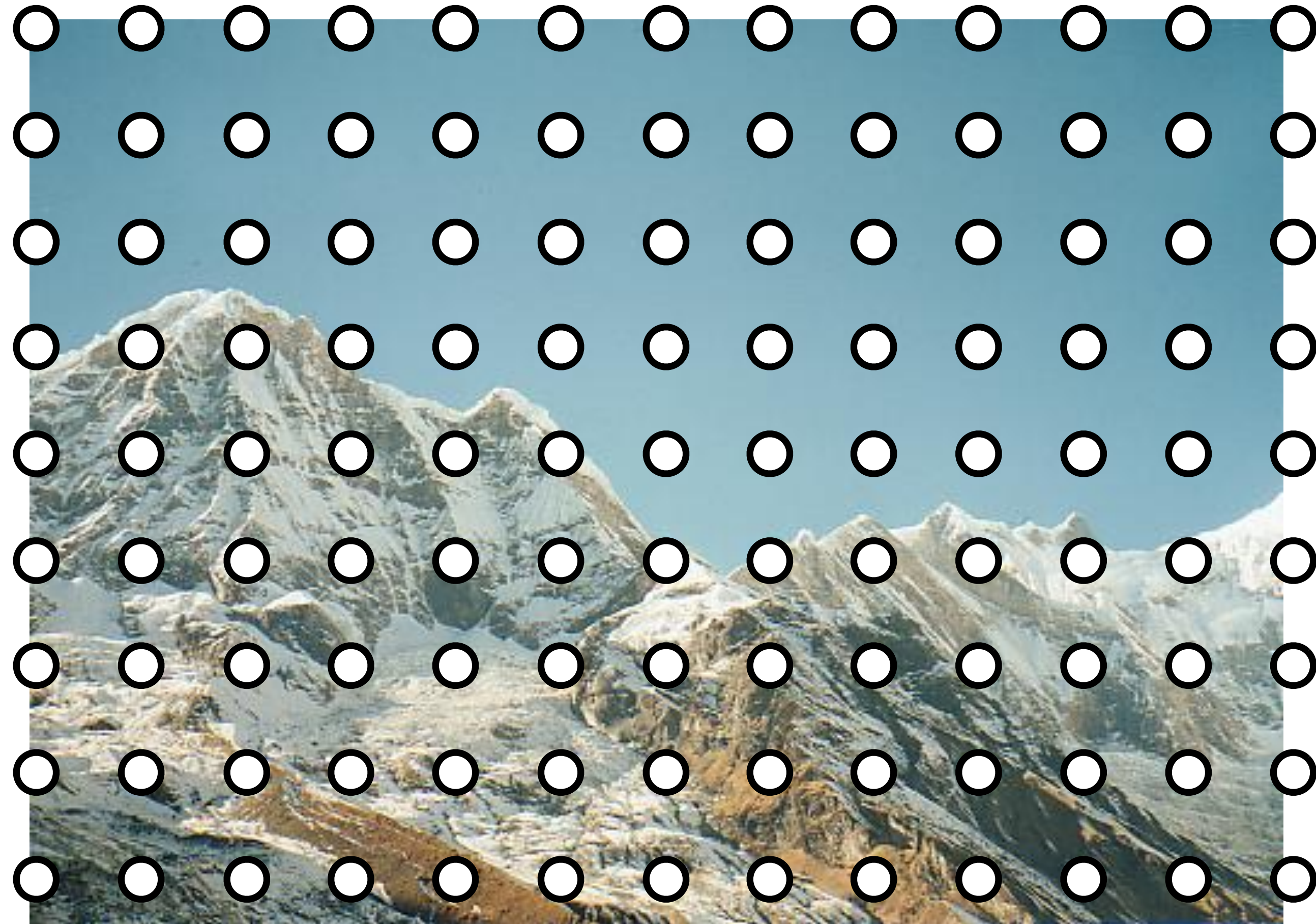
$I'(X, Y)$



changes domain of image function

# Resampling Images

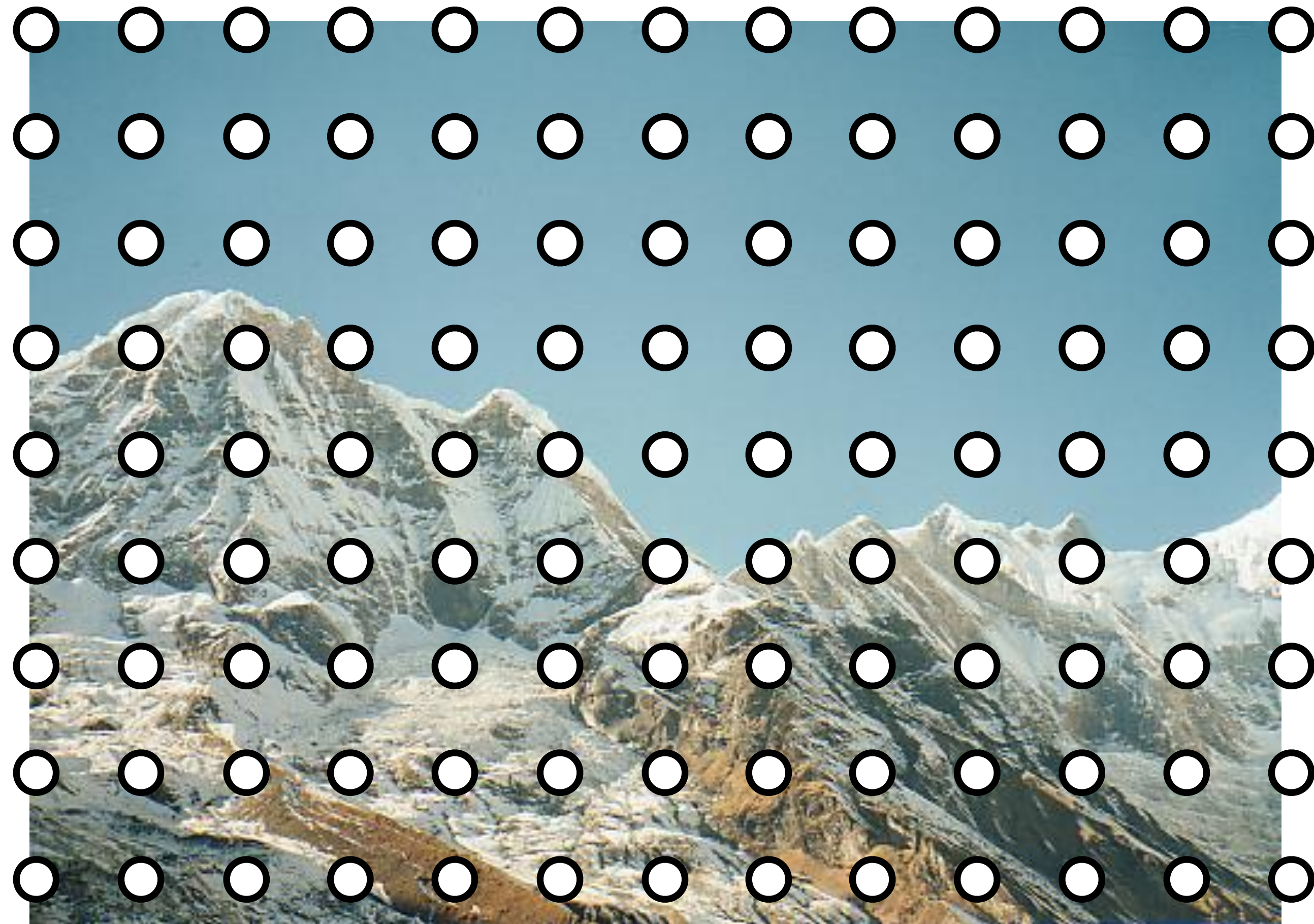
**Goal:** Resample the image to get a lower resolution counterpart



What is the simplest way to do this (e.g., produce image 1/5 of original size)?

# Resampling Images

**Goal:** Resample the image to get a lower resolution counterpart



**Naive Method:** Form new image by taking every  $n$ -th pixel of the original image

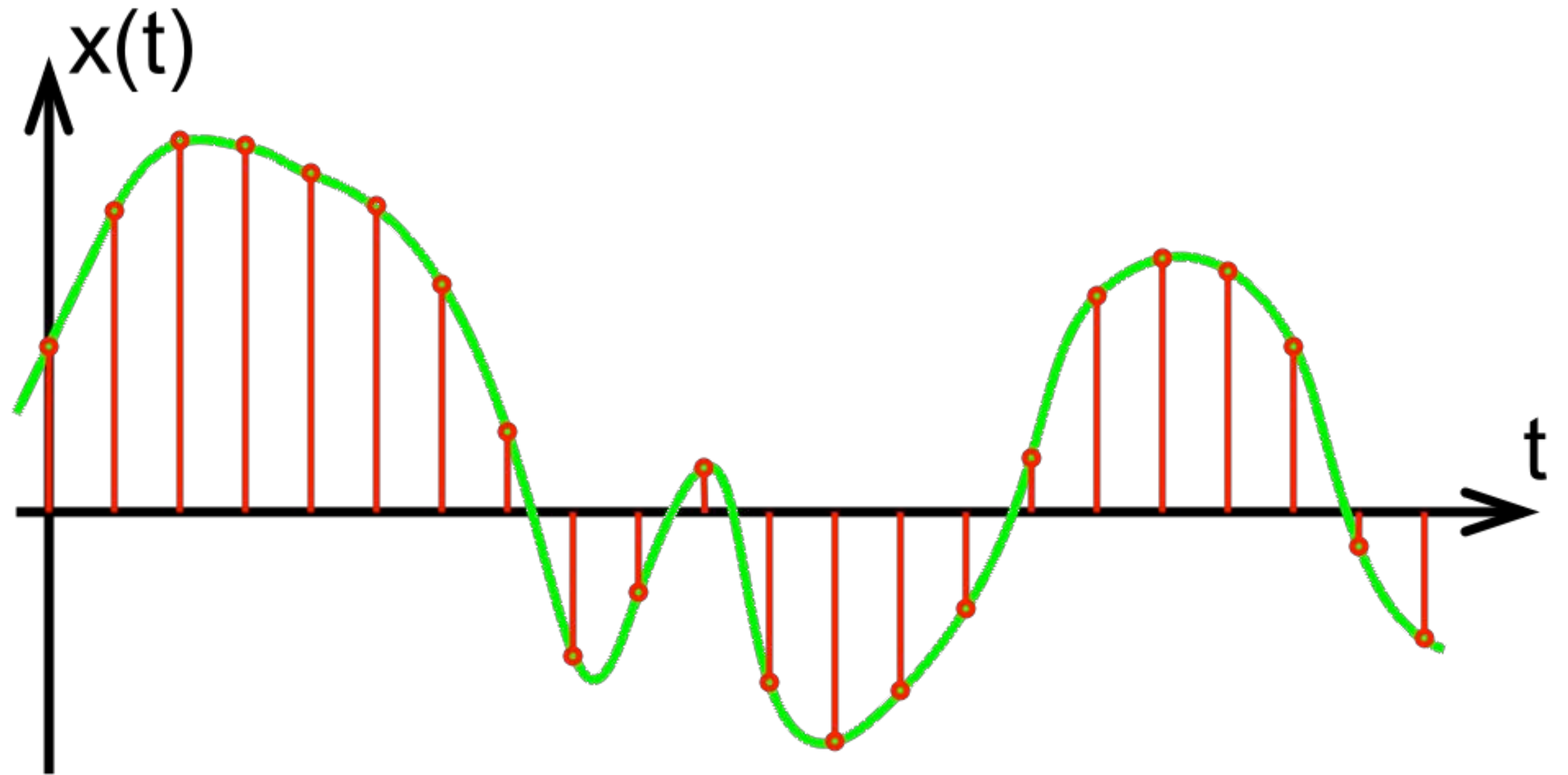
# Resampling Images

Sampling every 5-th pixel, while shifting rightwards one pixel at a time



What's wrong with this method?

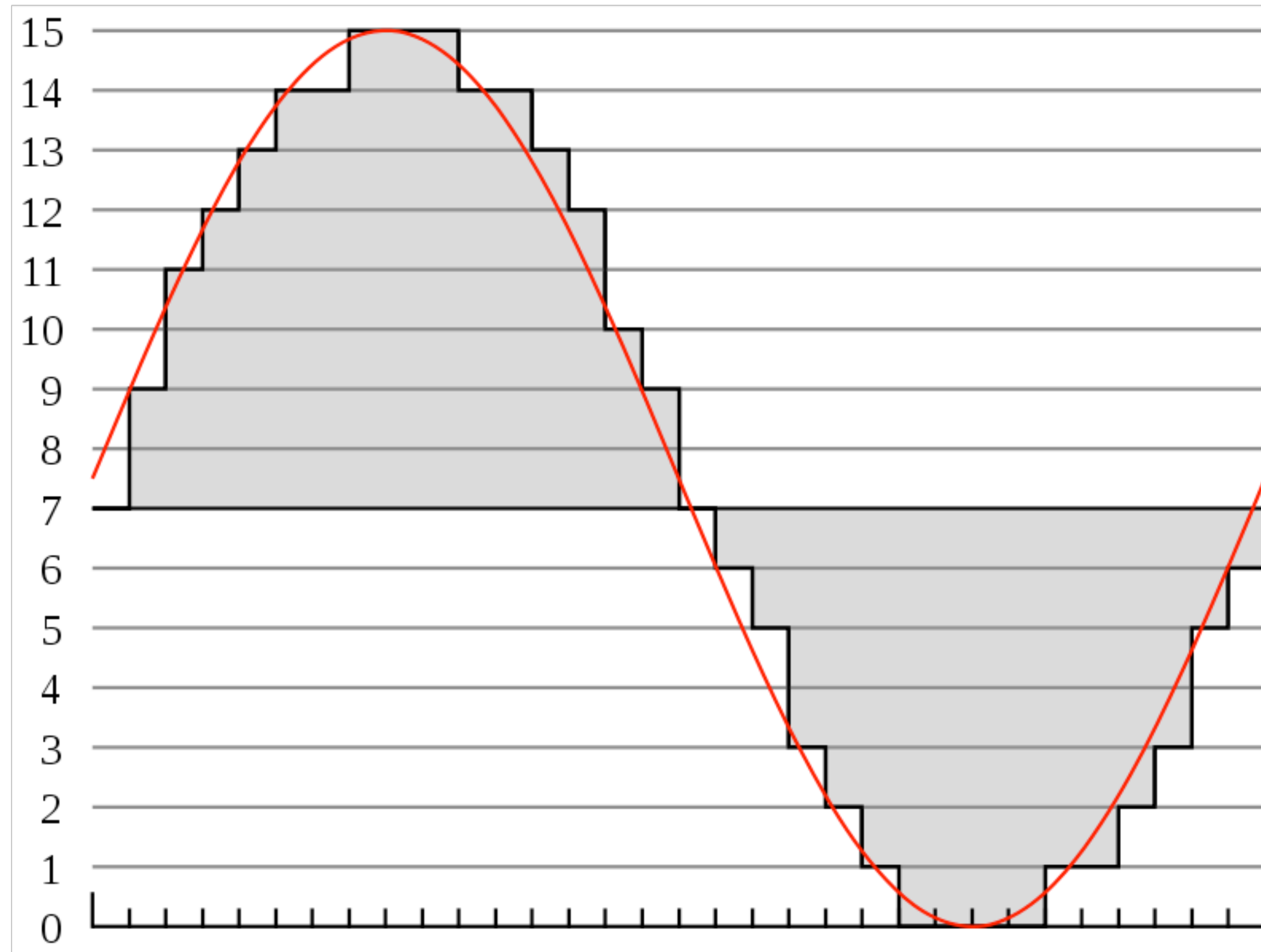
# Example: Audio Sampling



**Question:** What choice/parameters do we have when sampling audio signal?

Sampling rate and bit depth, e.g., 44.1 kHz (samples/second), 16 bits/sample

# Example: Audio Sampling

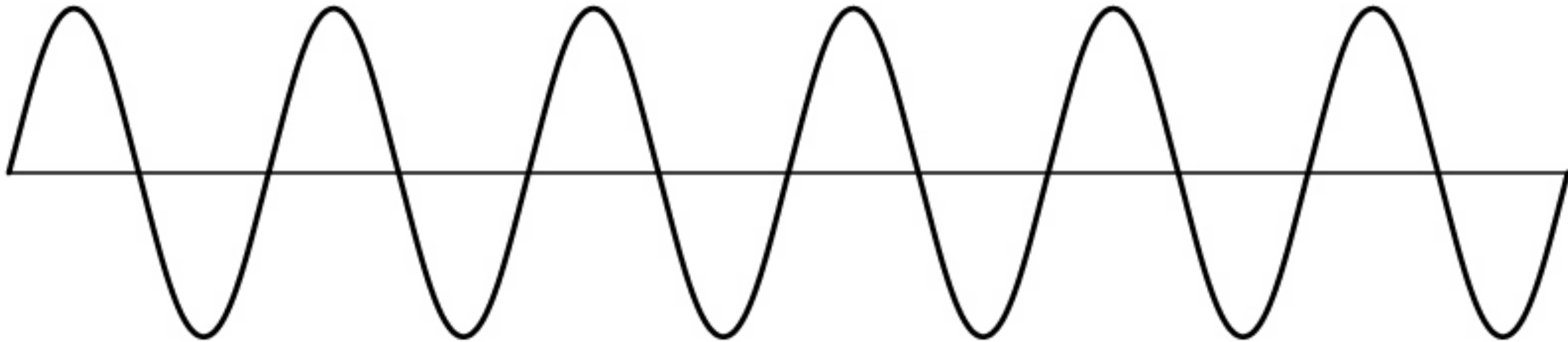


Quantization noise / error is the difference between black and red curves



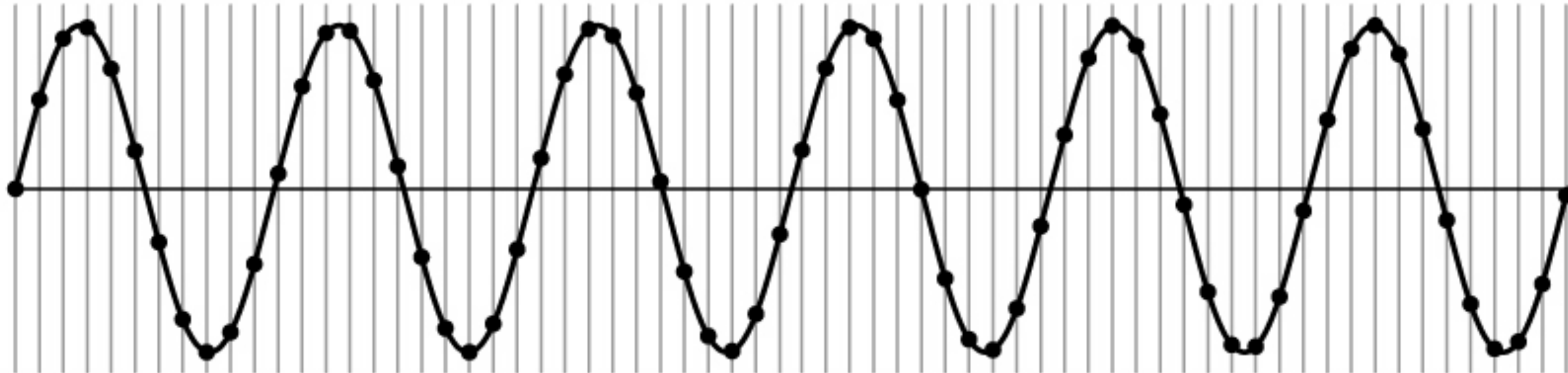
# Example: A Simple Sine Wave

How do we discretize the signal?



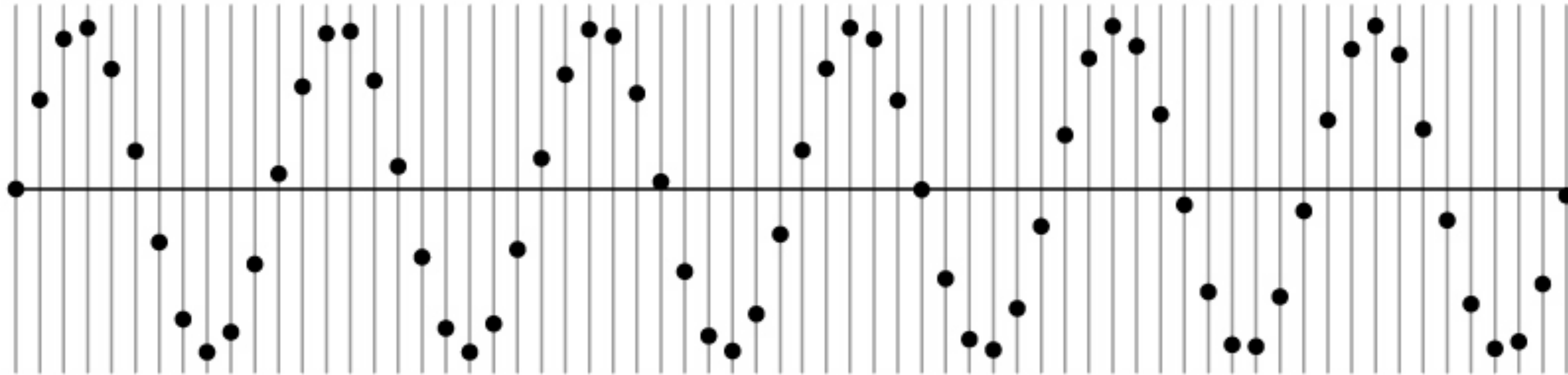
# Example: A Simple Sine Wave

How do we discretize the signal?



# Example: A Simple Sine Wave

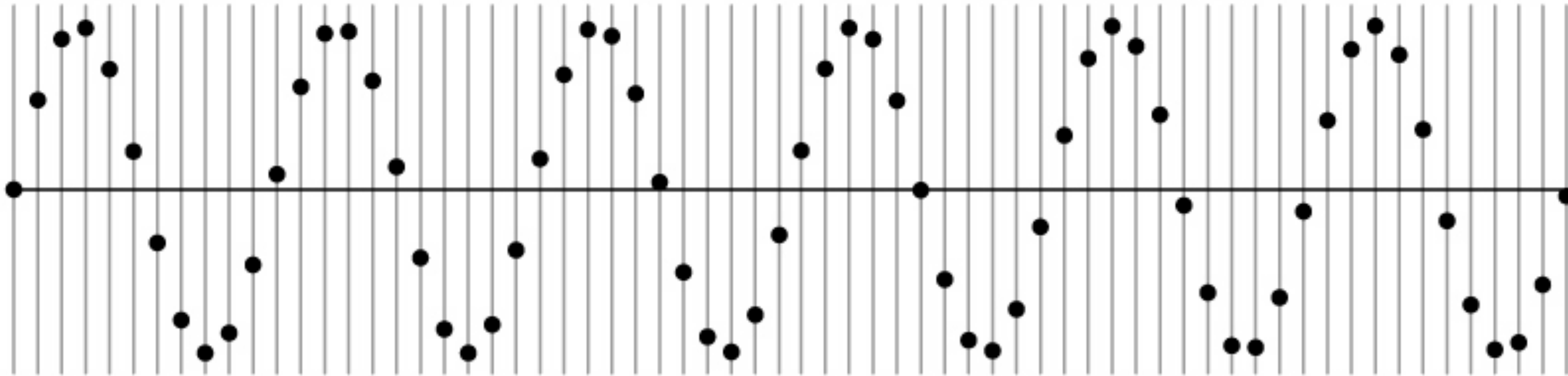
How do we discretize the signal?



How many samples should I take?  
Can I take as many samples as I want?

# Example: A Simple Sine Wave

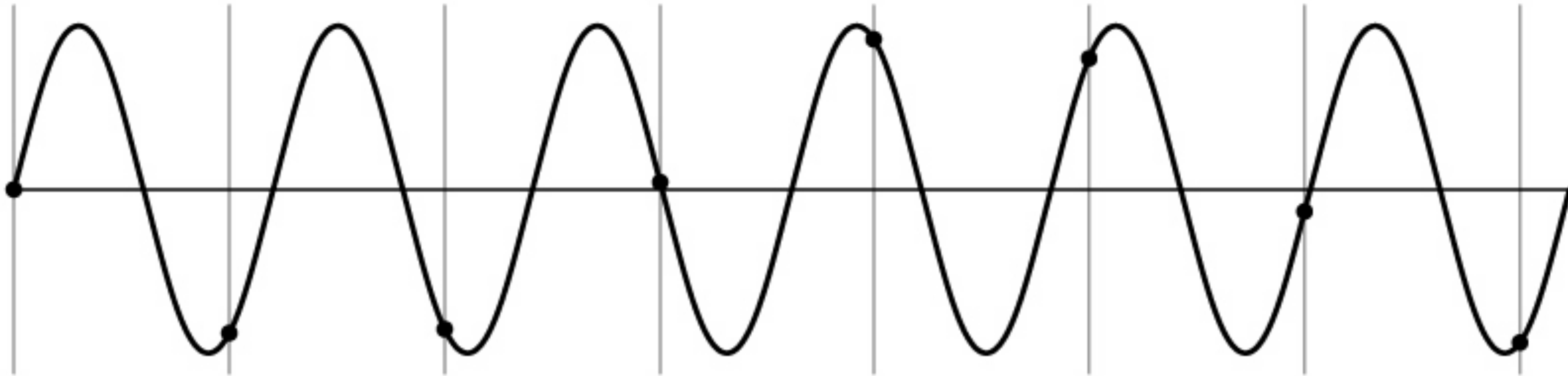
How do we discretize the signal?



How many samples should I take?  
Can I take as few samples as I want?

# Example: A Simple Sine Wave

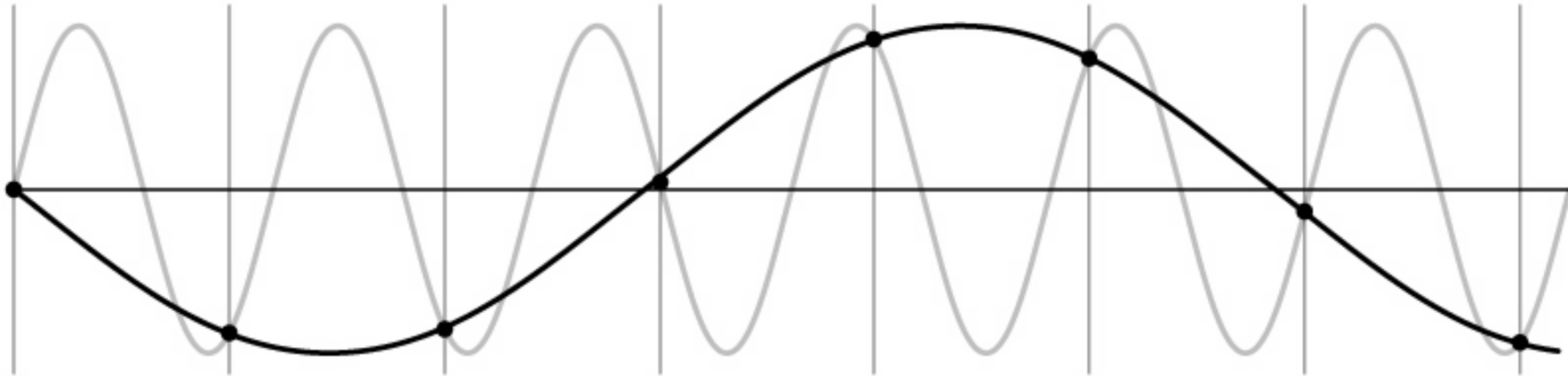
How do we discretize the signal?



Signal can be confused with one at lower frequency

# Example: A Simple Sine Wave

How do we discretize the signal?



Signal can be confused with one at lower frequency  
— This is called “Aliasing”

# Audio Aliasing

- Aliasing causes undesirable artifacts in audio reproduction
- e.g., if we take an audio signal and simply drop every second sample, the highest frequencies will be aliased... we hear robotic sounding distortion

```
import scipy.io.wavfile as wavfile

rate, signal = wavfile.read("stevie.wav")

data=signal[0:(rate*10),:] # 10 seconds of audio

data_2=data[0:-1:2,:] # select every 2nd sample
data_4=data[0:-1:4,:] # select every 4th sample
data_8=data[0:-1:8,:] # select every 8th sample

wavfile.write('test2.wav', int(rate/2), data_2)
wavfile.write('test4.wav', int(rate/4), data_4)
wavfile.write('test8.wav', int(rate/8), data_8)
```

Original

↓ 2

↓ 4

↓ 8

# Audio **Aliasing**

- We can reduce the aliasing artifacts by **pre-filtering** with a low pass filter
- e.g., if we apply smoothing with a Gaussian filter standard deviation 2.0 for each octave (factor 2) of downsampling we get a better result:

↓ 8

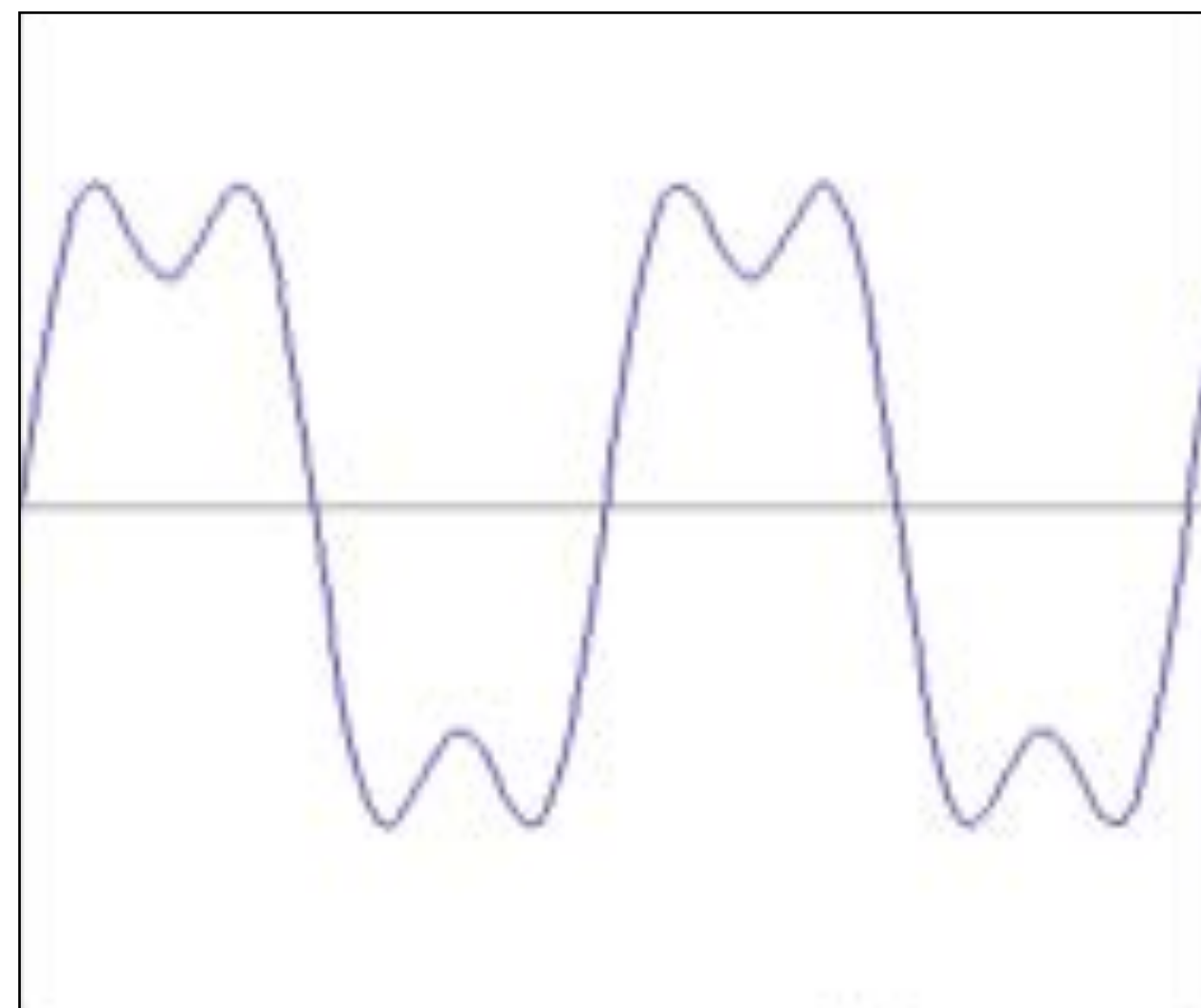
↓ 8 with pre-filtering

- Note we have still lost some of the high frequency content, but the crunchy sounding distortion due to aliasing has now gone

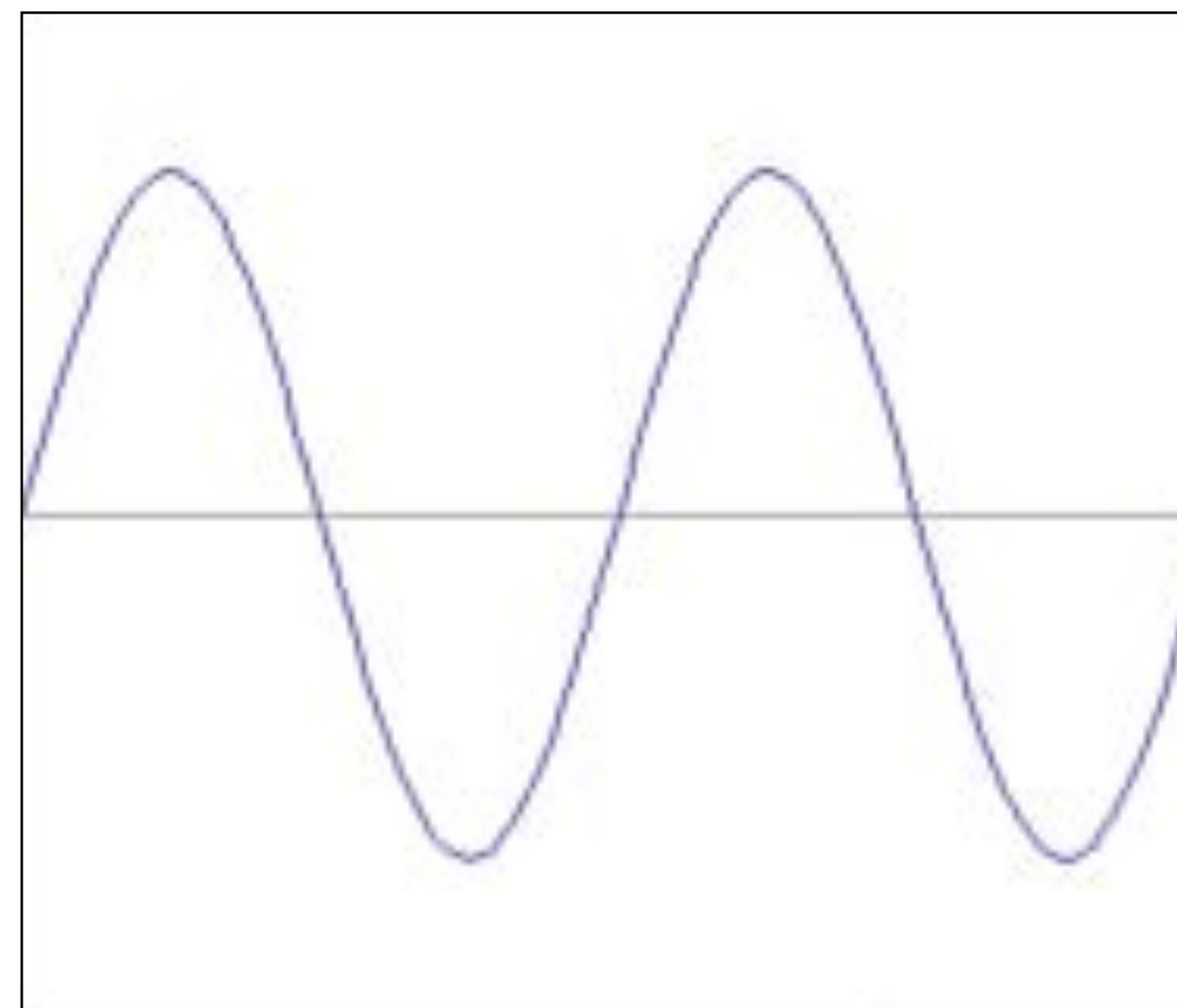


# Recall: **Fourier** Representation

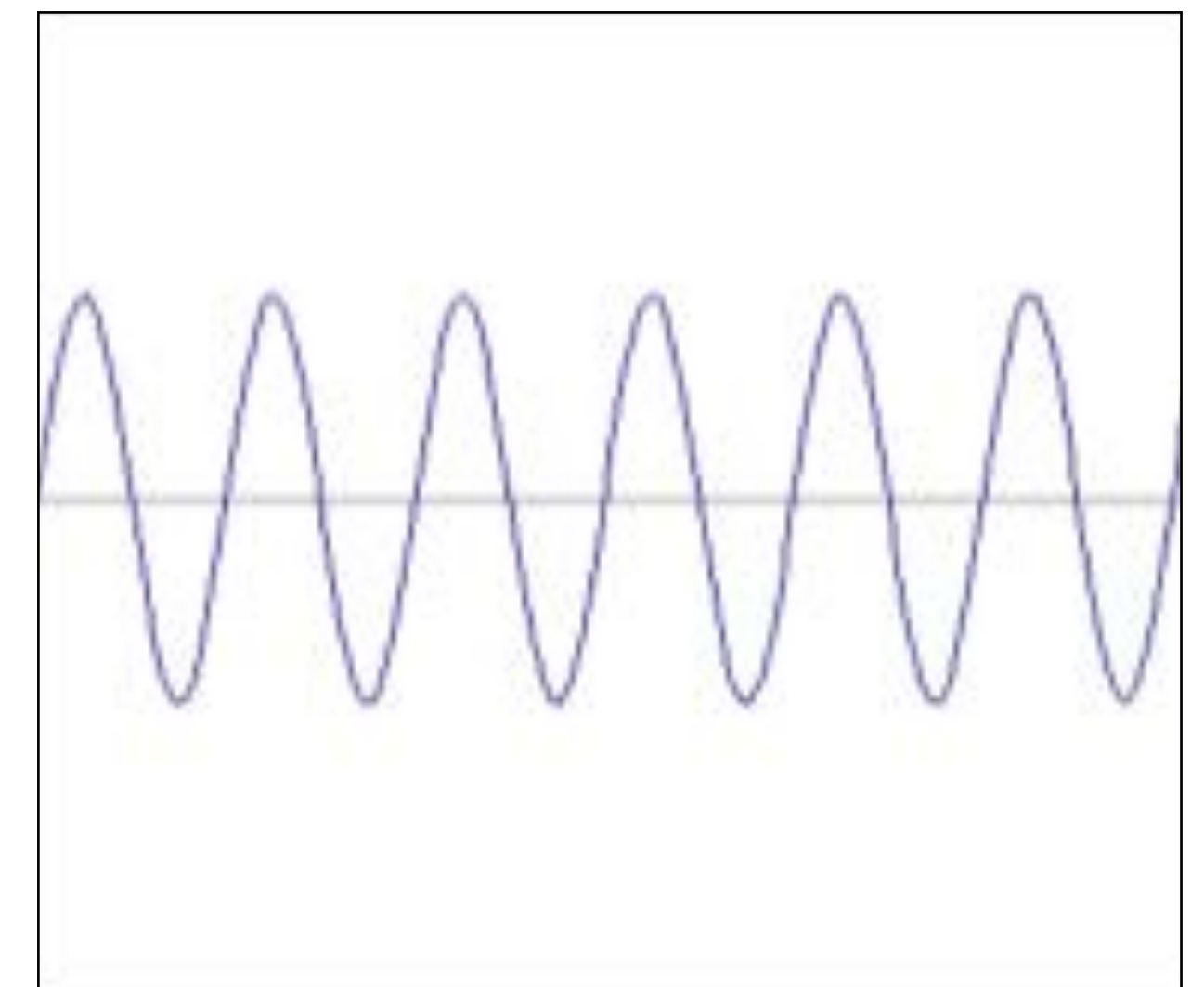
Any signal can be written as a sum of sinusoidal functions



=



+



$$f(x) = \sin(2\pi x) + \frac{1}{3} \sin(2\pi 3x)$$

$$\sin(2\pi x)$$

$$\frac{1}{3} \sin(2\pi 3x)$$

# Nyquist Sampling Theorem

To avoid aliasing a signal must be sampled at twice the maximum frequency:

$$f_s > 2 \times f_{max}$$

where  $f_s$  is the sampling frequency, and  $f_{max}$  is the maximum frequency present in the signal

Futhermore, Nyquist's theorem states that a signal is **exactly recoverable** from its **samples** if sampled at the **Nyquist rate** (or higher)

Note: that a signal must be **bandlimited** for this to apply (i.e., it has a maximum frequency)



6.1

# Exact **Reconstruction** from **Samples**

**Question:** When is  $I(X, Y)$  an exact characterization of  $i(x, y)$ ?

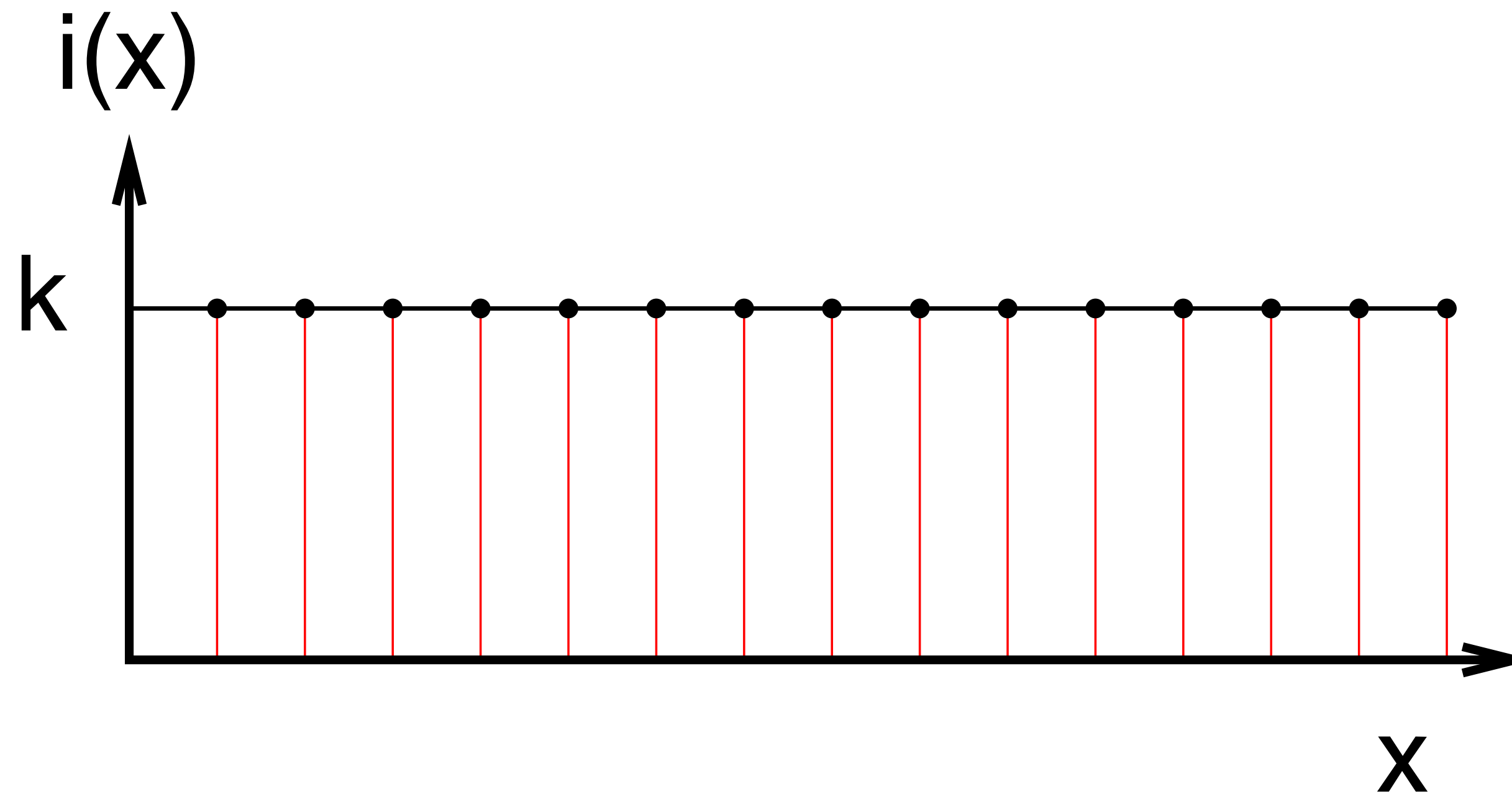
**Question** (modified): When can we reconstruct  $i(x, y)$  exactly from  $I(X, Y)$ ?

**Intuition:** Reconstruction involves some kind of **interpolation**

**Heuristic:** When in doubt, consider simple cases

# Sampling Theory (informal)

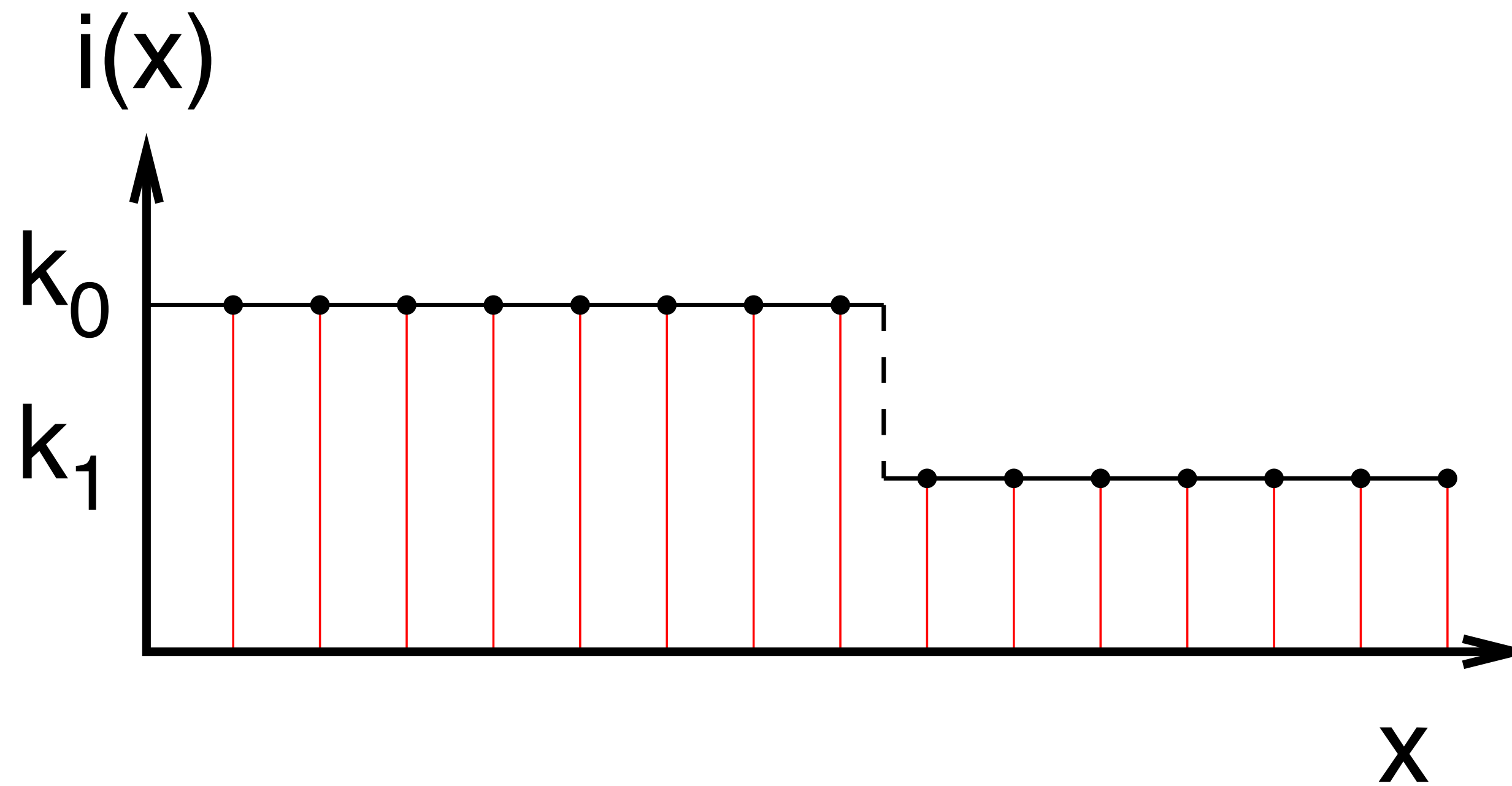
**Case 0:** Suppose  $i(x, y) = k$  (with  $k$  being one of our gray levels)



$I(X, Y) = k$ . Any standard interpolation function would give  $i(x, y) = k$  for non-integer  $x$  and  $y$  (irrespective of how coarse the sampling is)

# Sampling Theory (informal)

**Case 0:** Suppose  $i(x, y)$  has a discontinuity not falling precisely at integer  $x, y$

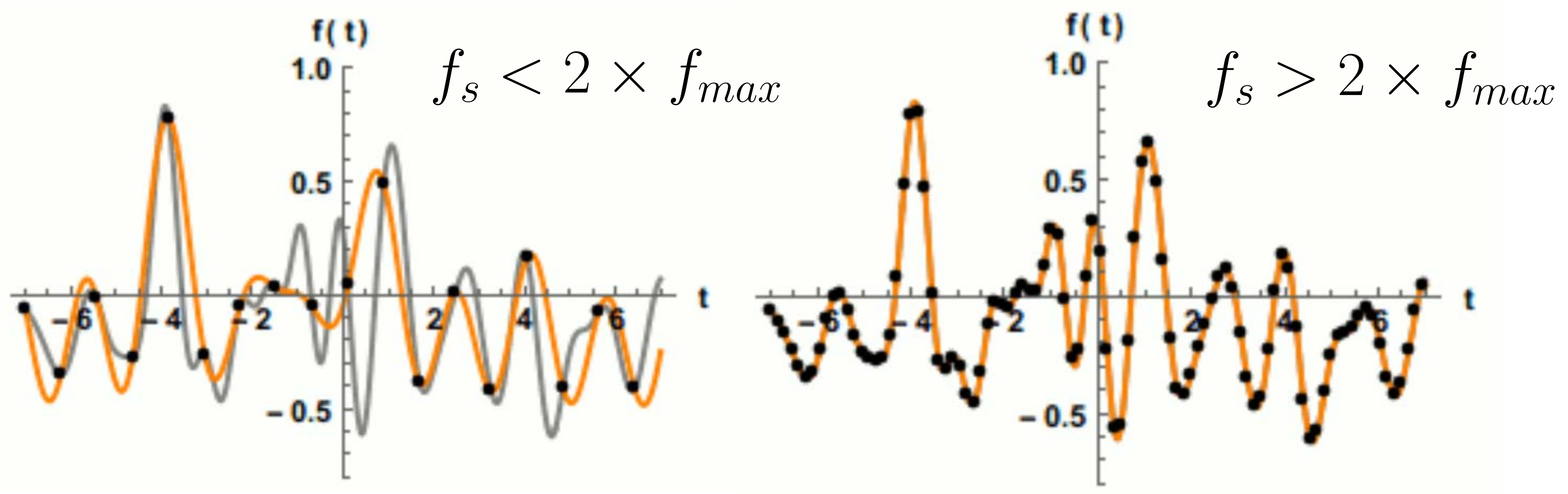


We cannot reconstruct  $i(x, y)$  exactly because we can never know exactly where the discontinuity lies

# Reconstruction with Bandlimited Signal

It can be shown that a bandlimited and correctly sampled signal can be reconstructed exactly via interpolation with a **sinc** function ( $\sin(x)/x$ )

(This is the Fourier Transform pair of a box filter, which in frequency domain is a pure low-pass filter)



# Sampling Theory (informal)

Exact reconstruction requires constraint on the rate at which  $i(x,y)$  can change between samples

- “rate of change” means derivative
- the formal concept is **bandlimited signal**
- “bandlimit” and “constraint on derivative” are linked

Think of music

- bandlimited if it has some maximum **temporal frequency**
- the upper limit of human hearing is about 20 kHz

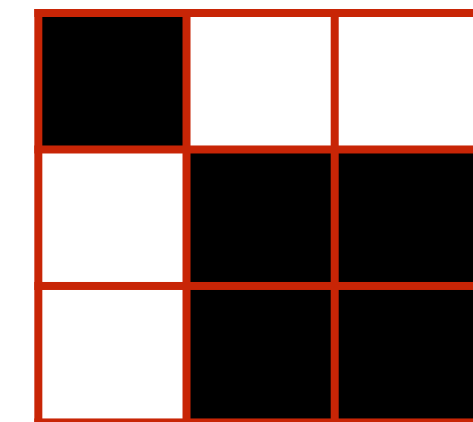
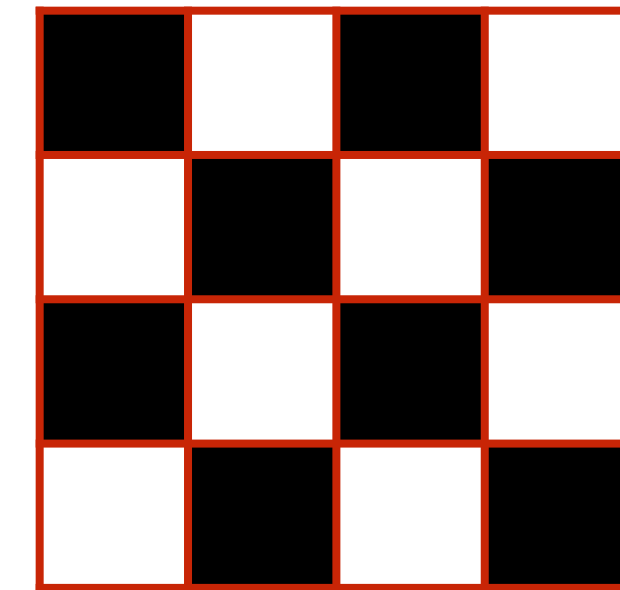
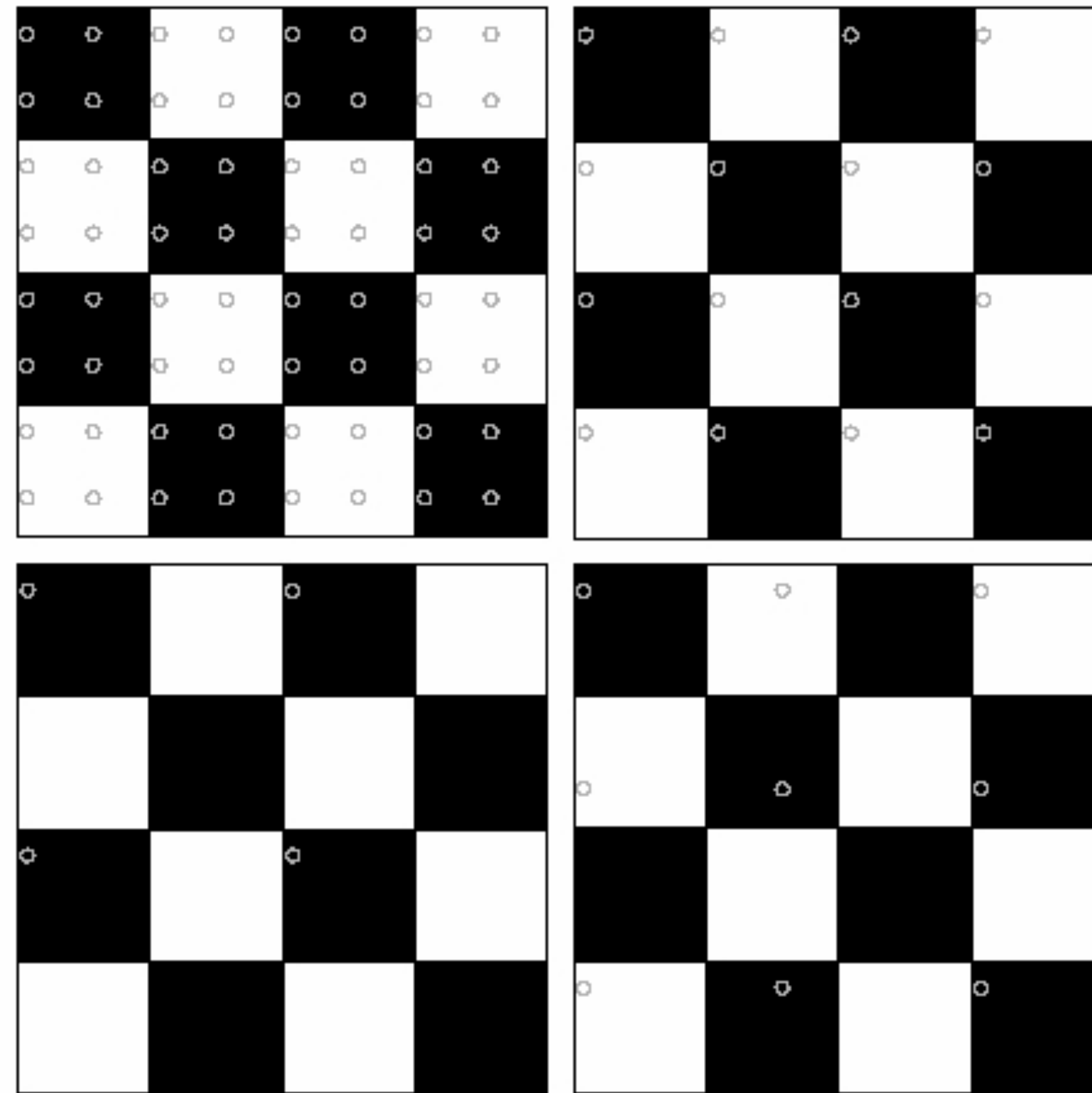
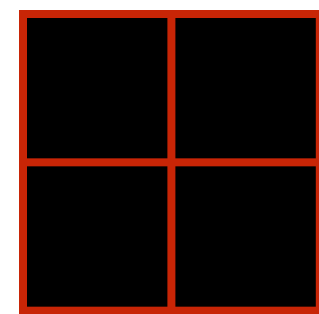
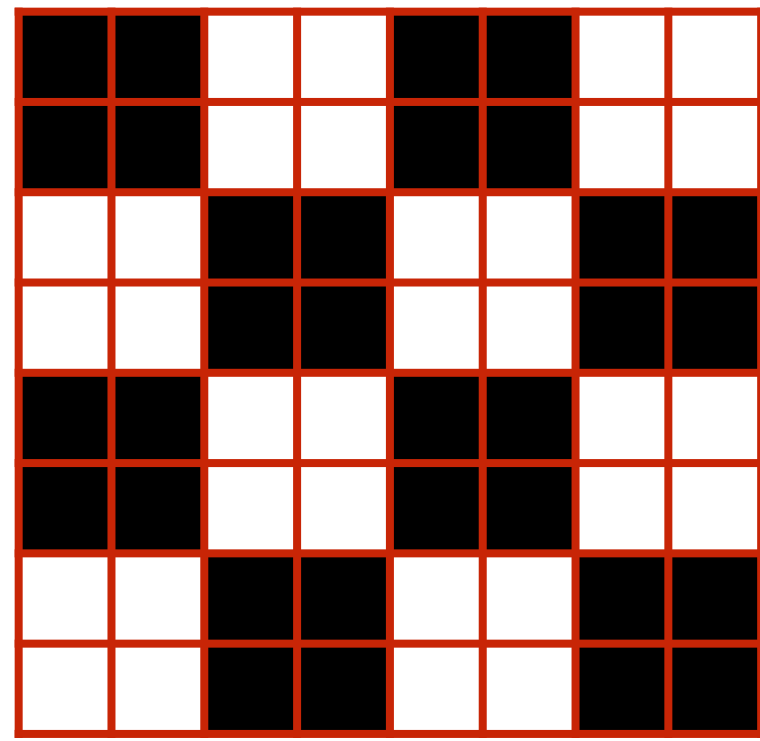
Think of imaging systems. Resolving power is measured in

- “line pairs per mm” (for a bar test pattern)
- “cycles per mm” (for a sine wave test pattern)

An image is bandlimited if it has some maximum **spatial frequency**

# Sampling

It is clear that *some* information may be lost when we work on a discrete pixel grid.



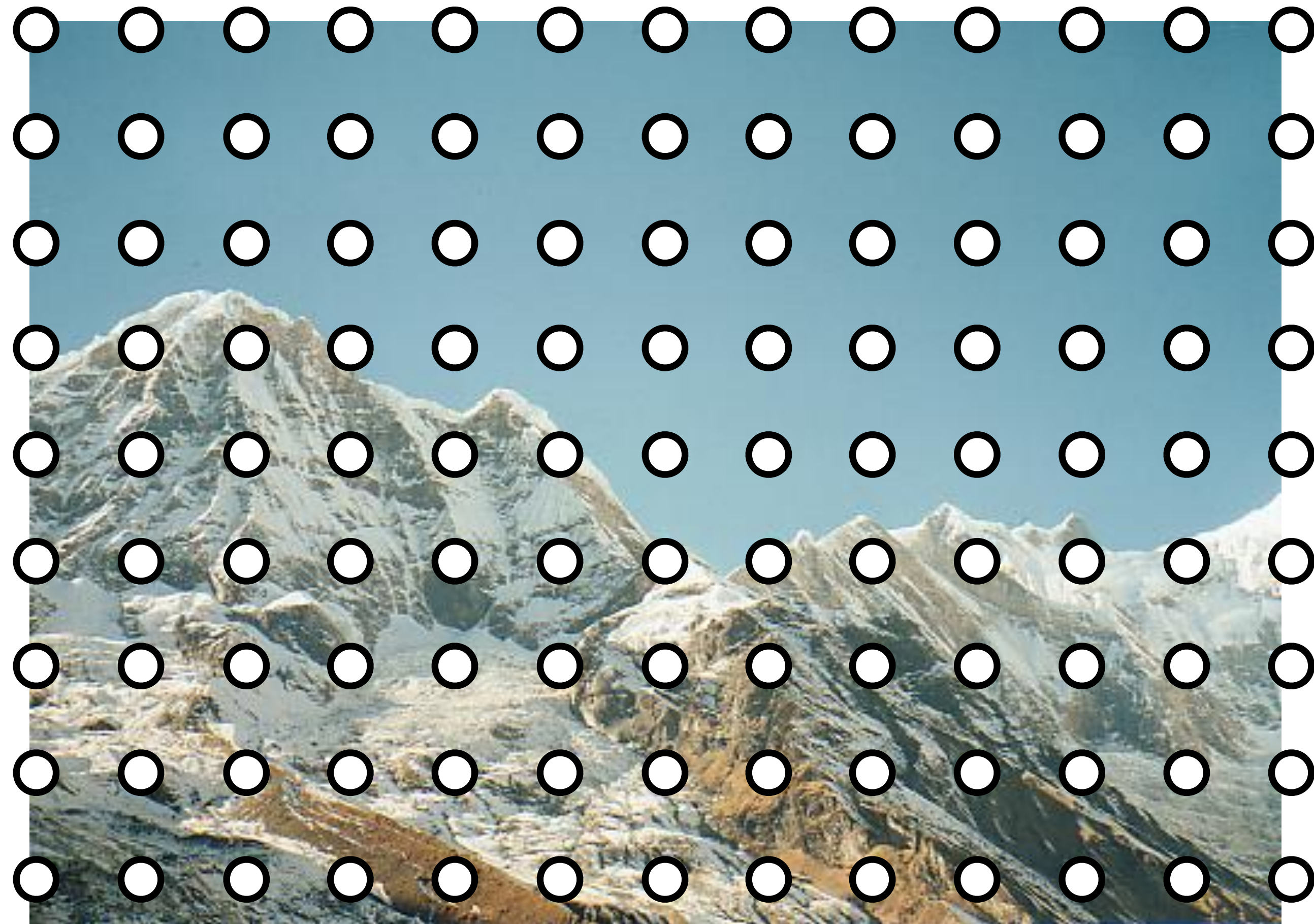
6.2

Forsyth & Ponce (2nd ed.) Figure 4.7



# Resampling Images

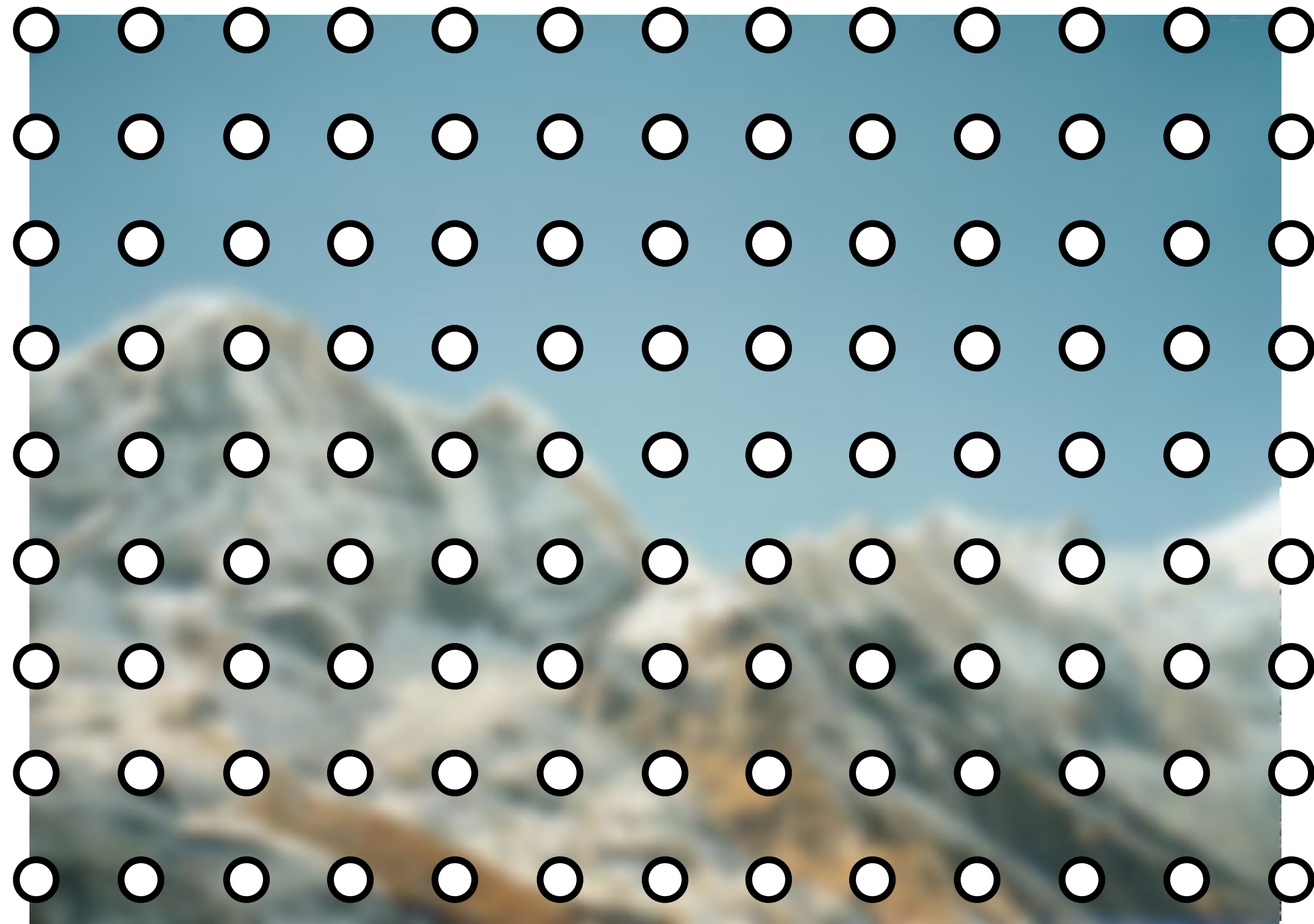
**Goal:** Resample the image to get a lower resolution counterpart



**Naive Method:** Form new image by taking every  $n$ -th pixel of the original image

# Resampling Images

With correct sigma value for a Gaussian, no information is lost



**Improved Method:** First blur the image (with low-pass) then take n-th pixel

# Aliasing Example

Sampling every 5th pixel with and without low-pass blur



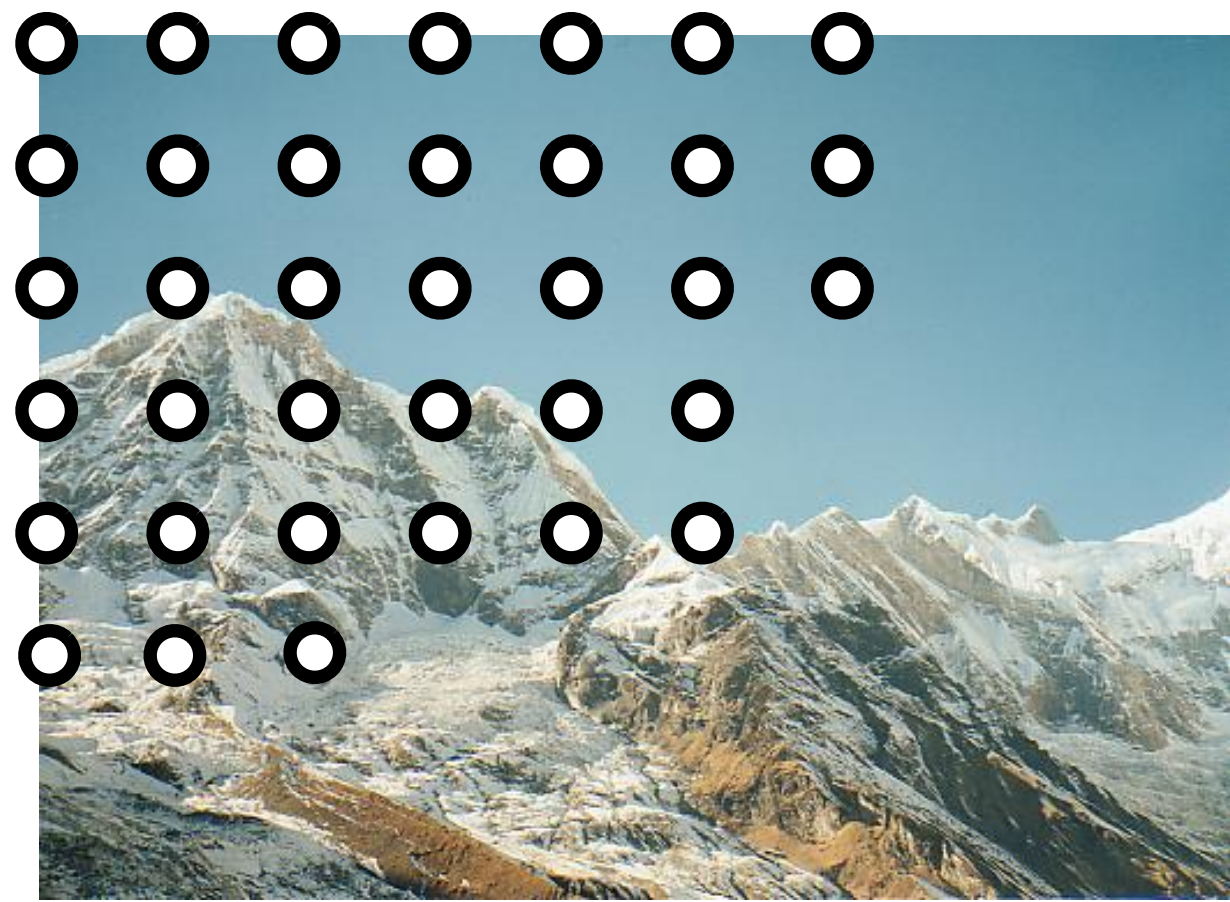
No filtering



Gaussian Blur  $\sigma = 3.0$

$$\sigma = 1/(2s)$$

# Resampling Images



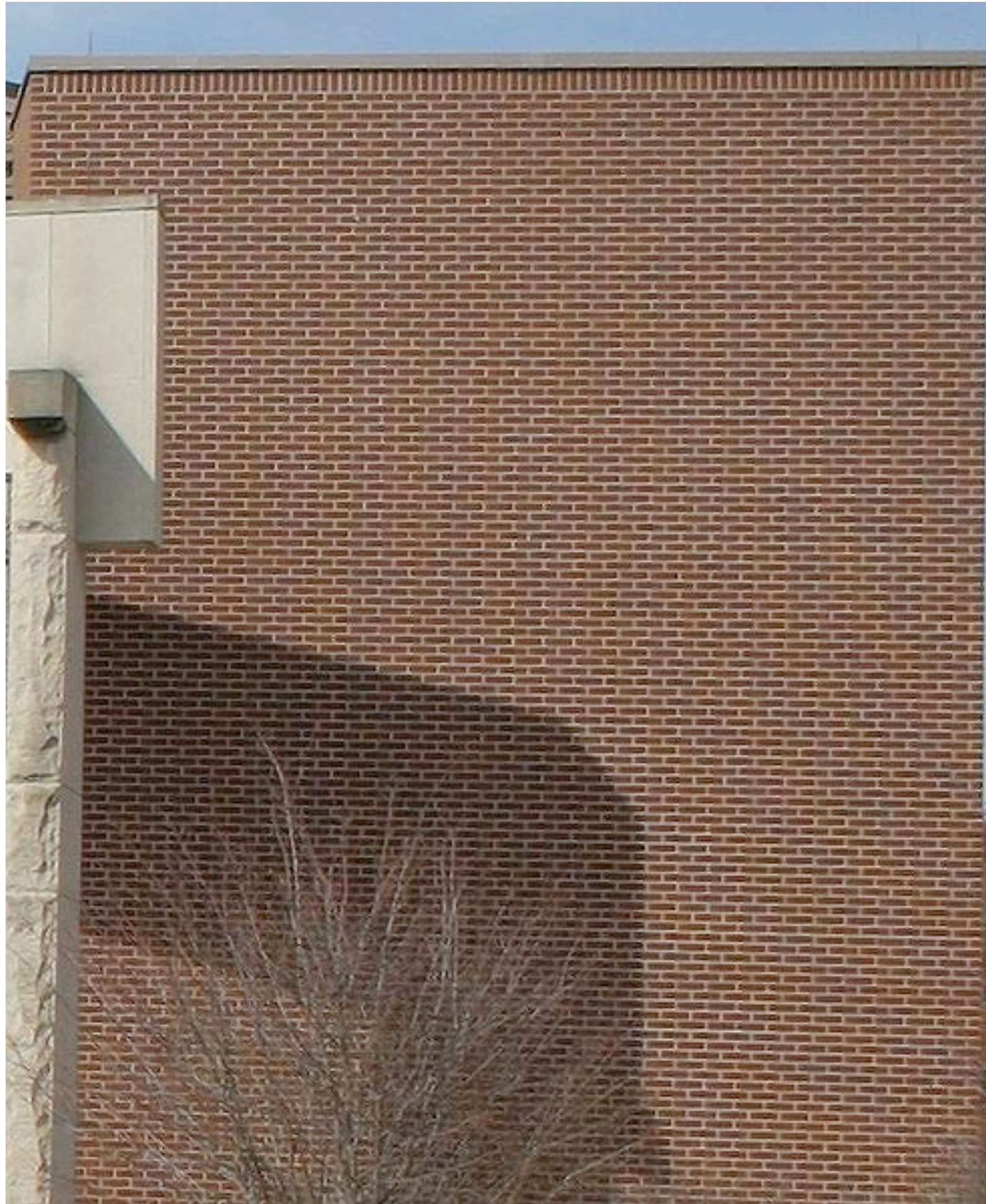
**every 10th pixel**  
(aliased)



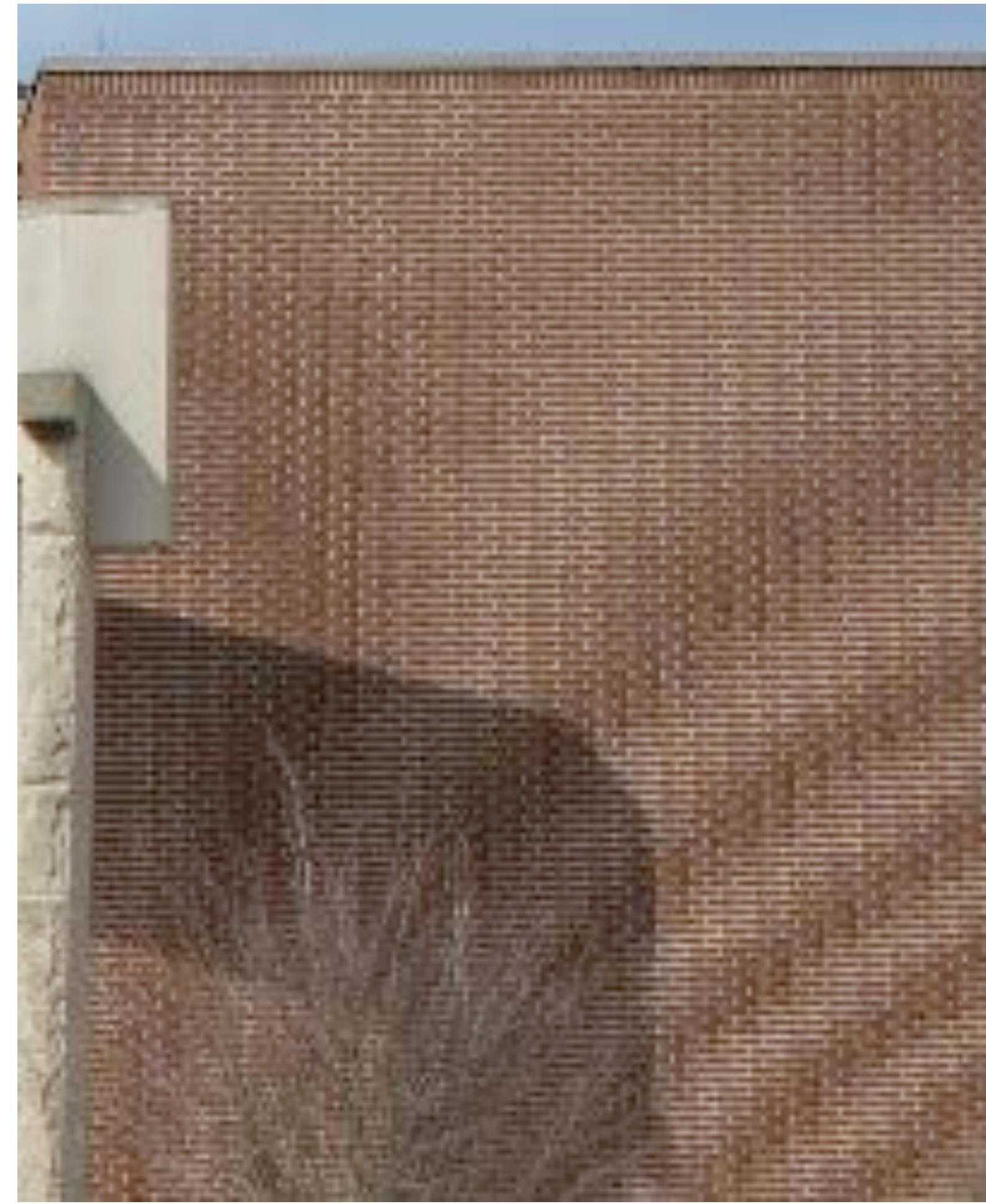
**low pass filtered**  
(correct sampling)

- Note that selecting every 10th pixel ignores the intervening information, whereas the low-pass filter (blur) smoothly combines it
- If we shifted the original image 1 pixel to the right, the aliased image would look completely different, but the low pass filtered image would look almost the same

# Image Sampling and Aliasing

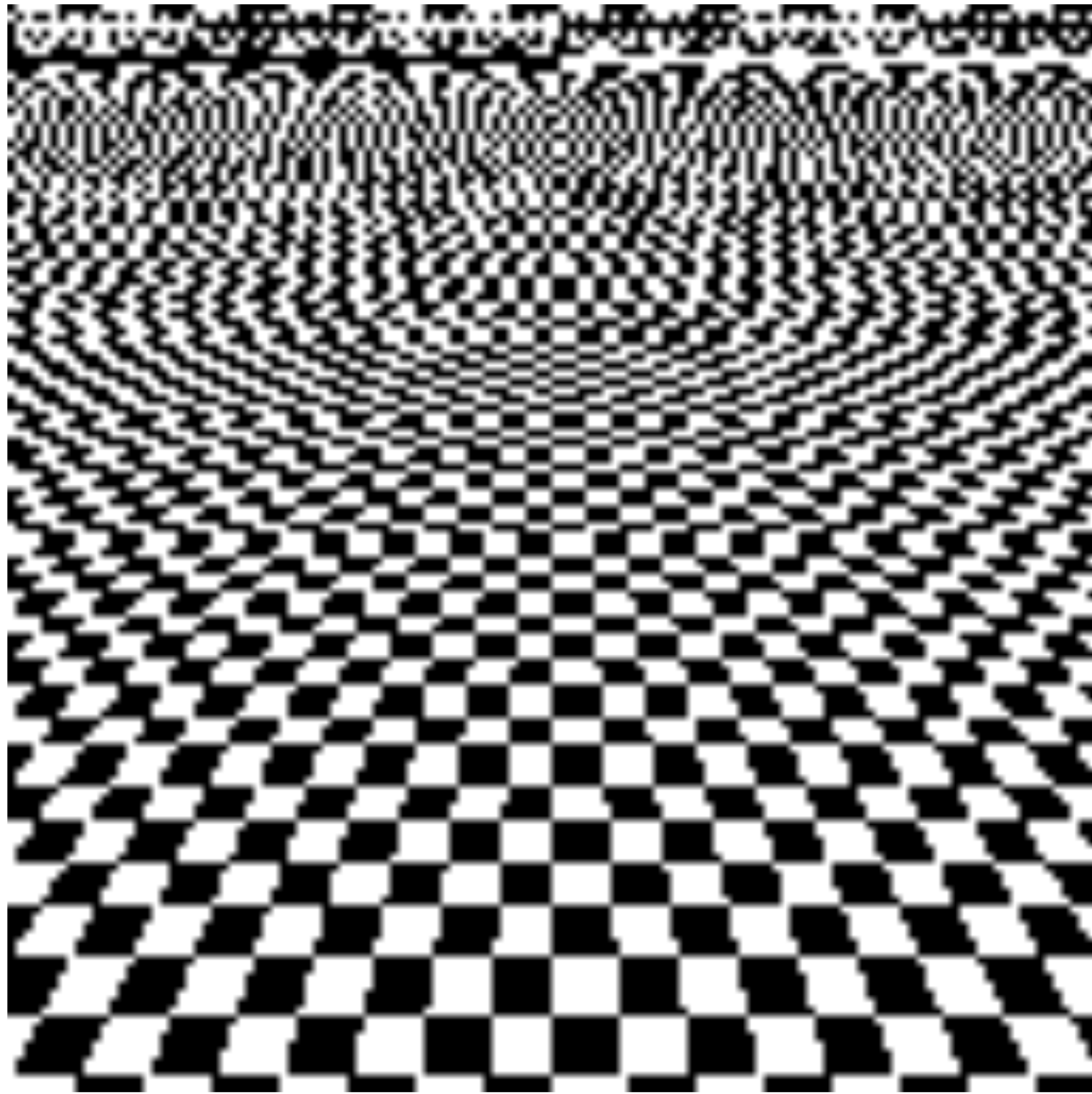


$$f_s > 2 \times f_{max}$$

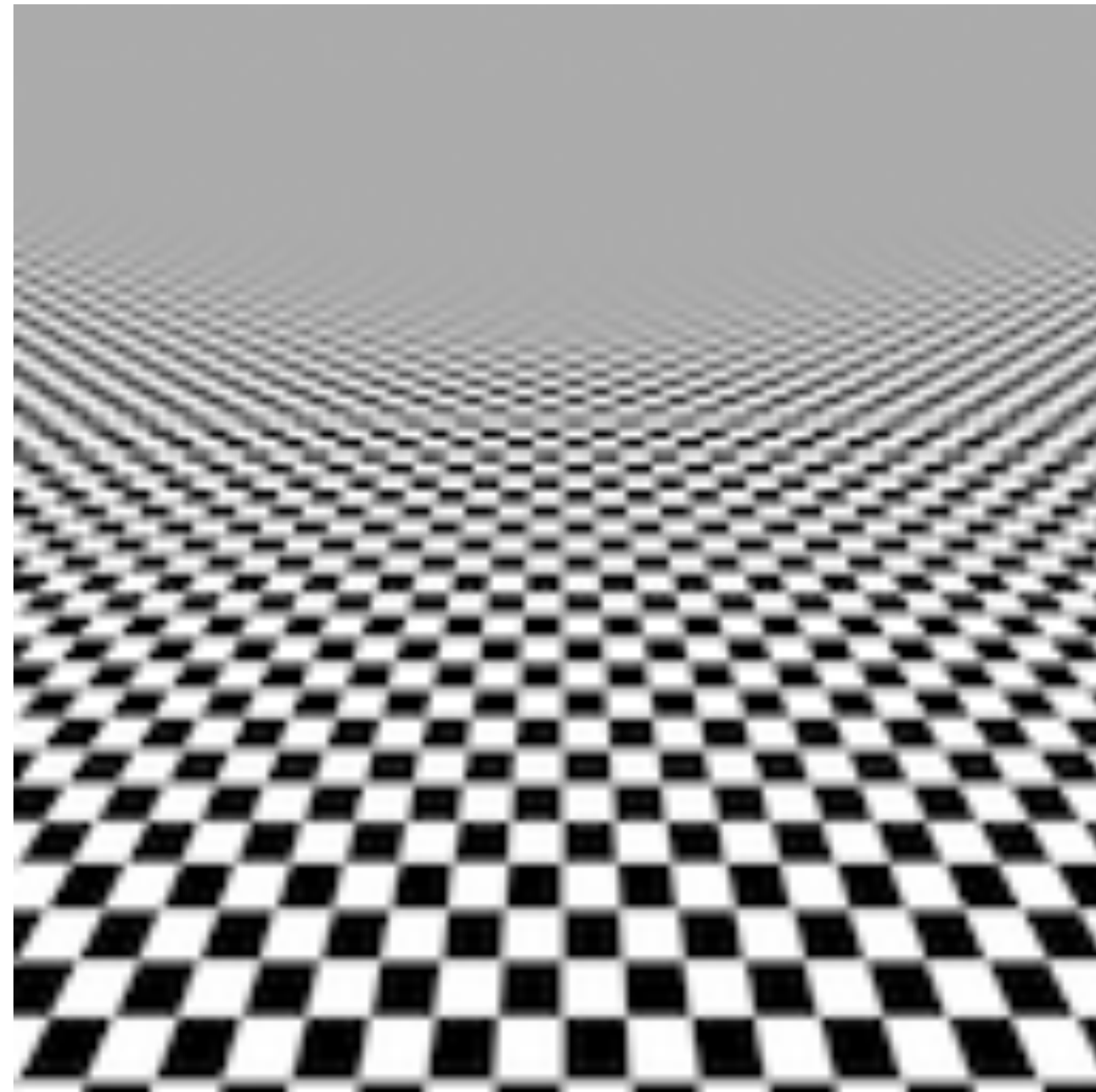


$$f_s < 2 \times f_{max}$$

# Another example of aliasing



Aliased



Correctly sampled

# Aliasing in Photographs

This is also known as “moire”



# Image Pyramids



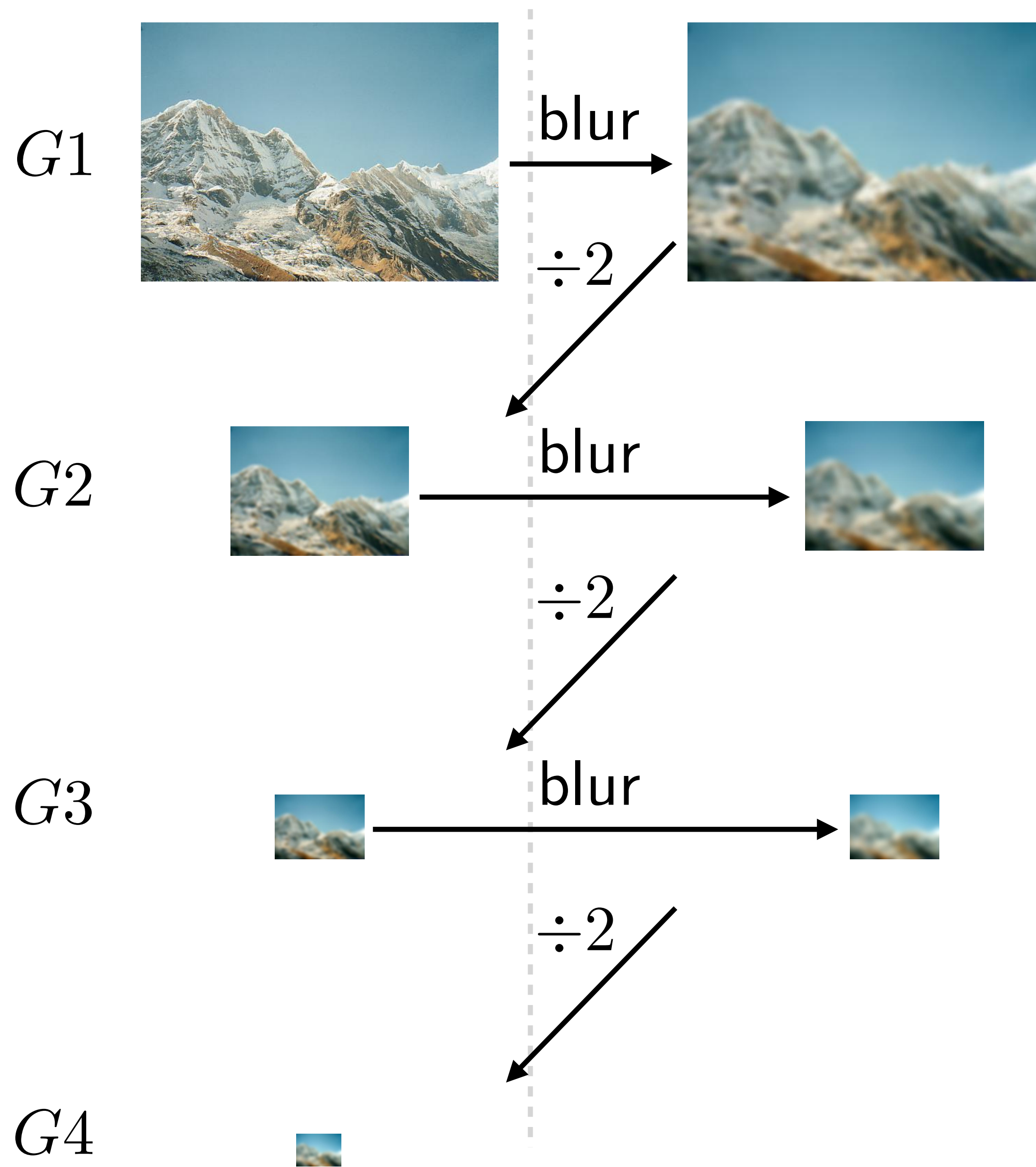
↙ ÷2

↙ ÷2

↙ ÷2

Used in Graphics (Mip-map) and Vision  
(for **multi-scale** processing)





Blur with a Gaussian kernel, then select every 2nd pixel

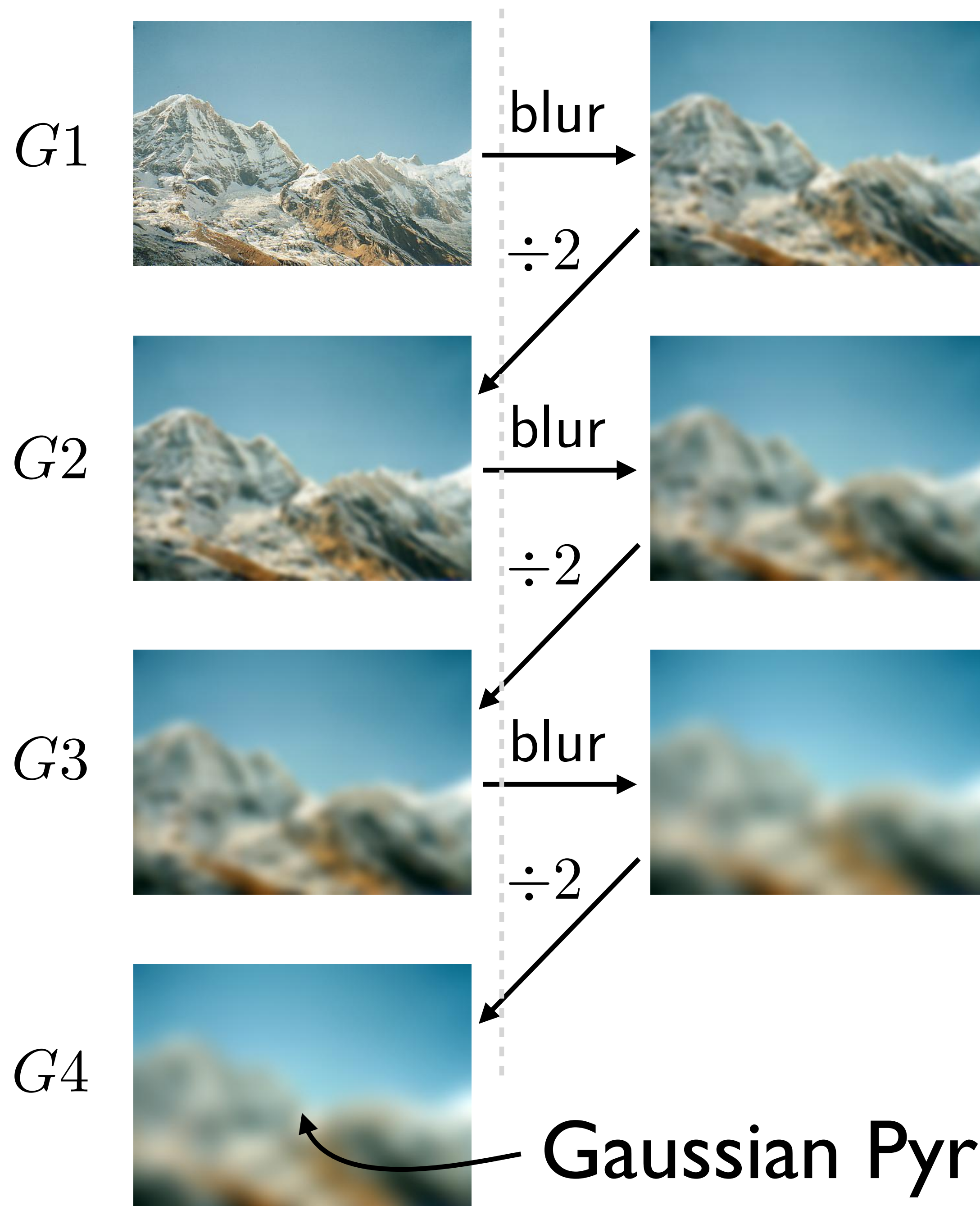
$$I_s(x, y) = I(x, y) * g_\sigma(x, y)$$

Often approximations to the Gaussian kernel are used, e.g.,

$$\frac{1}{16} \begin{bmatrix} 1 & 4 & 6 & 4 & 1 \end{bmatrix}$$

**Gaussian Pyramid**

[ Assignment 2 ]



Blur with a Gaussian kernel, then select every 2nd pixel

$$I_s(x, y) = I(x, y) * g_\sigma(x, y)$$

Often approximations to the Gaussian kernel are used, e.g.,

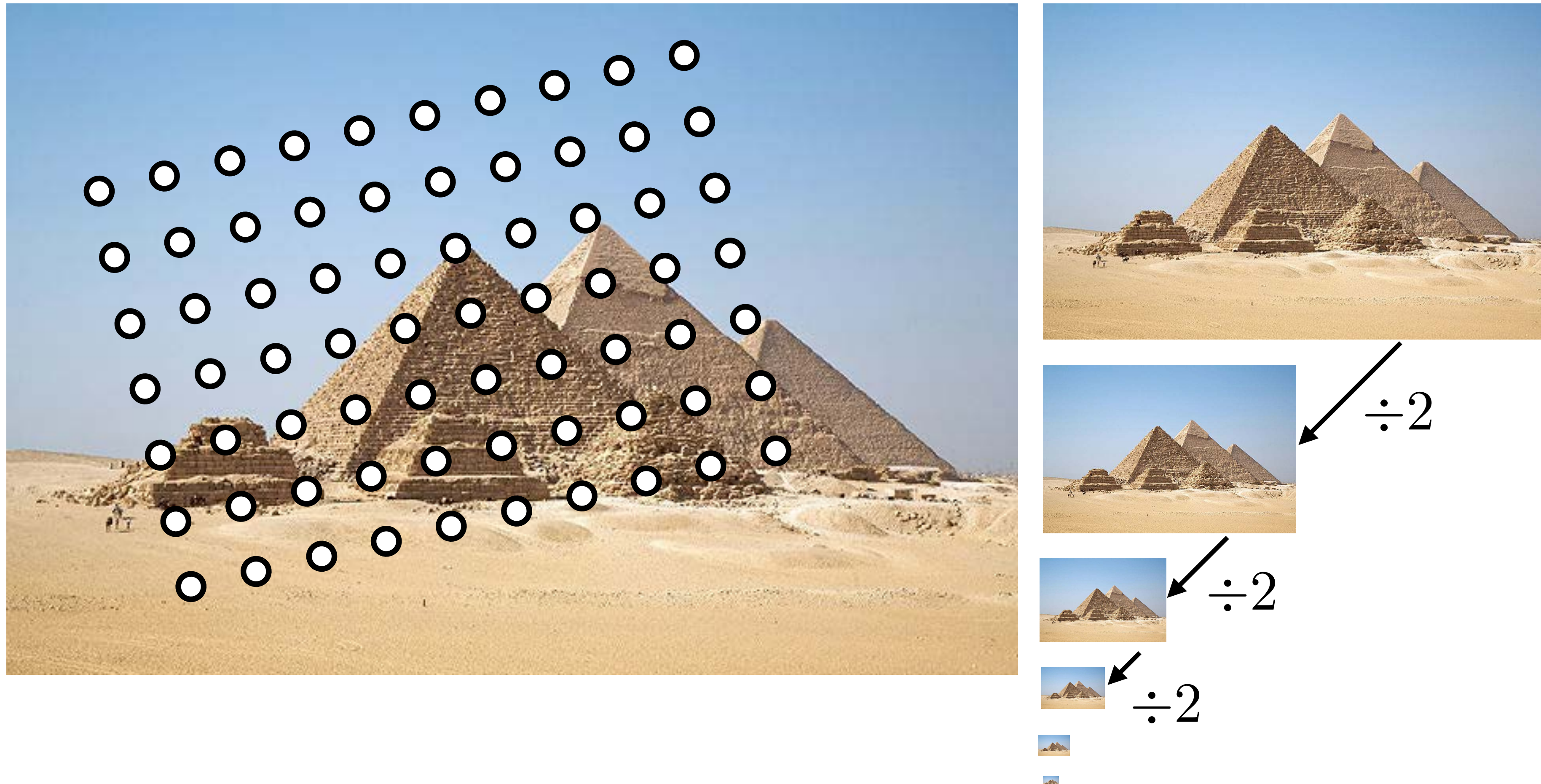
$$\frac{1}{16} \begin{bmatrix} 1 & 4 & 6 & 4 & 1 \end{bmatrix}$$

**Gaussian Pyramid**

[ Assignment 2 ]

# Sampling with Pyramids

Why are image pyramids important?



Find the level where the sample spacing is between 1 and 2 pixels, apply extra fraction of inter-octave blur as needed

# Oversampling and Undersampling

**Question:** For a bandlimited signal, what if you **oversample** (i.e., sample at greater than the Nyquist rate)

**Answer:** Nothing bad happens! Samples are redundant and there are wasted bits

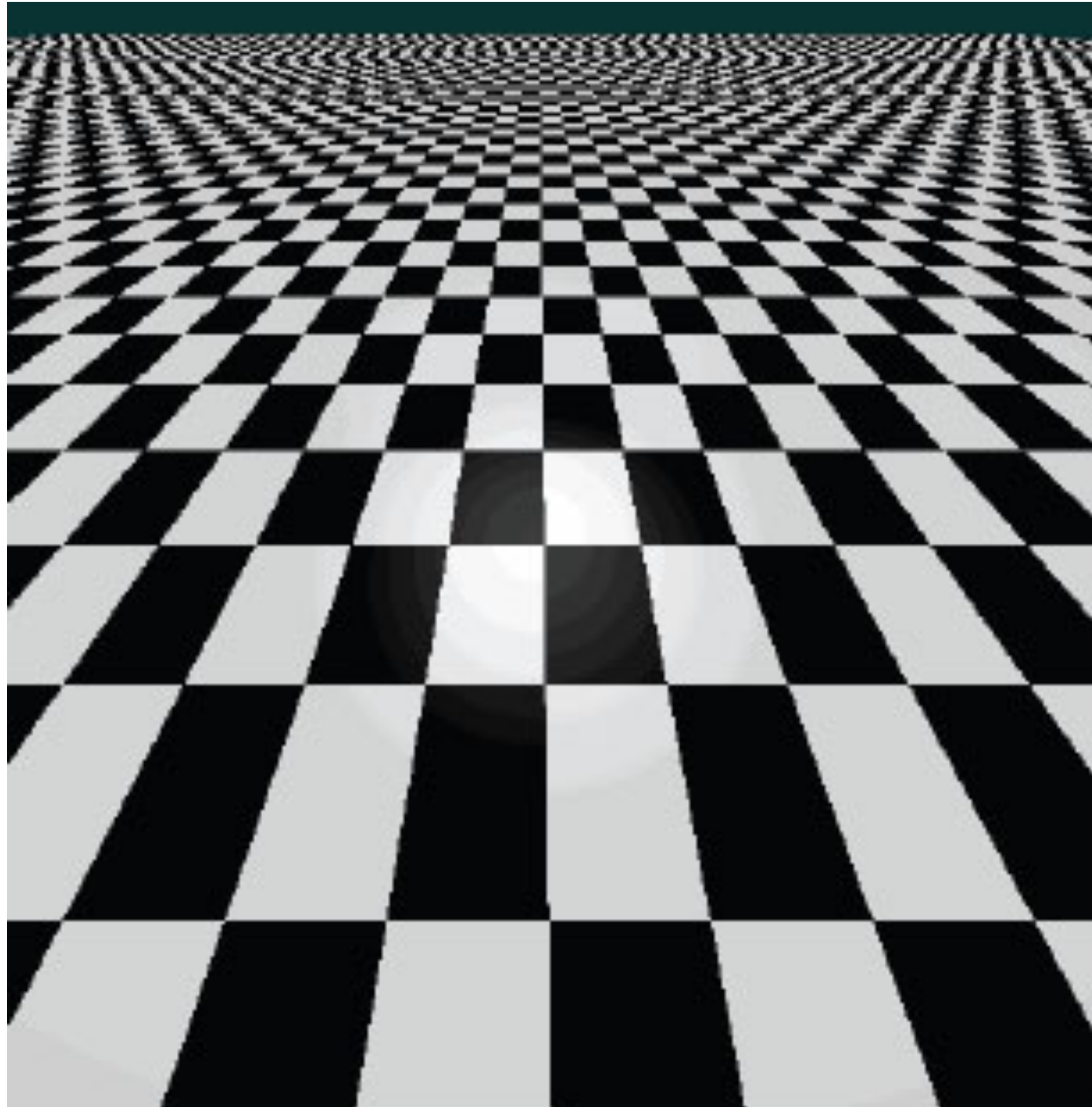
**Question:** For a bandlimited signal, what if you **undersample** (i.e., sample at less than the Nyquist rate)

**Answer:** Two bad things happen! Things are missing (i.e., things that should be there aren't). There are artifacts (i.e., things that shouldn't be there are)

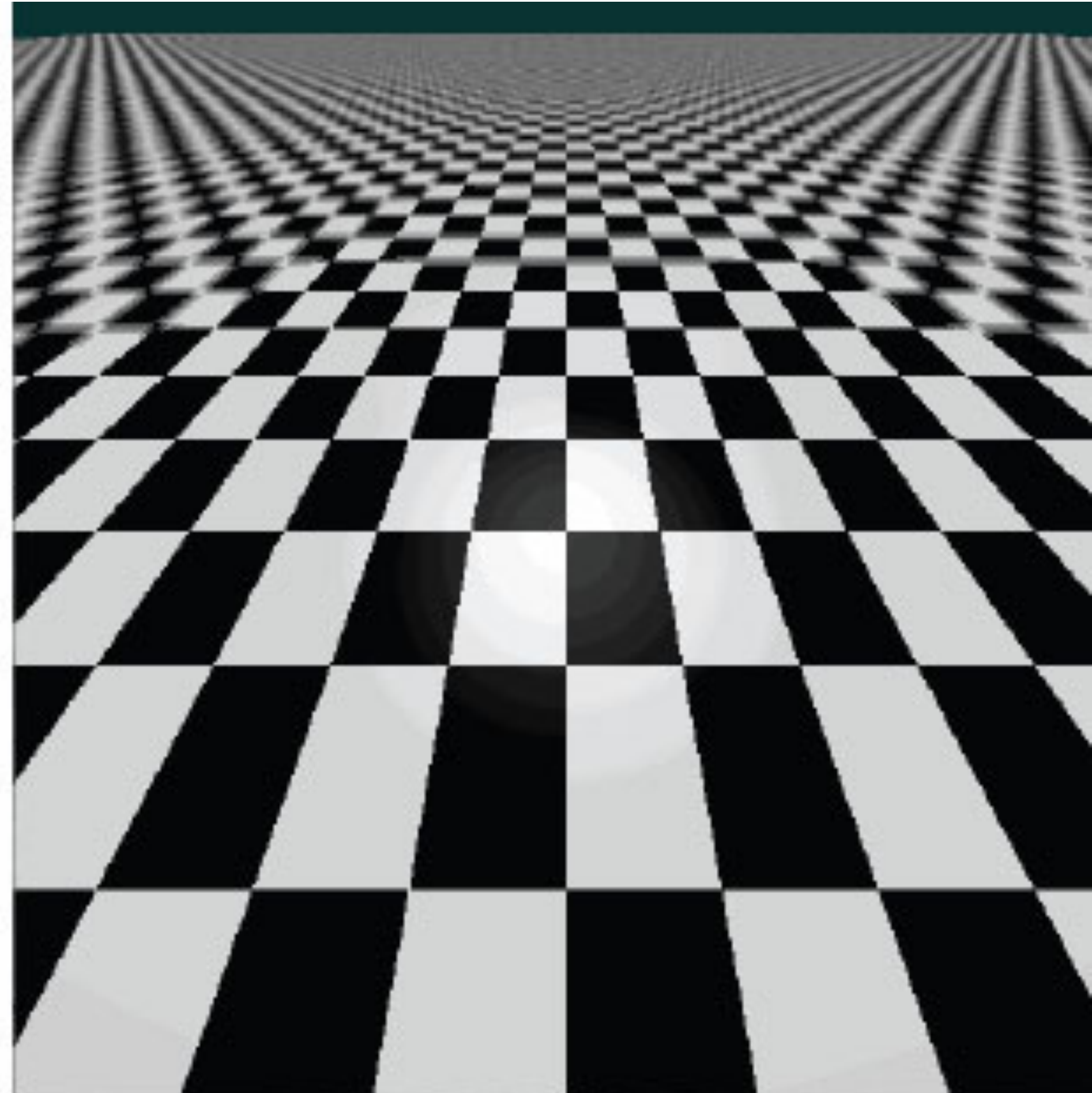
# How to Prevent **Aliasing**?

1. **Sample more frequently** i.e., oversampling — sample more than you think you need and average (i.e., area sampling)
2. **Reduce the maximum frequency**, by low pass filtering i.e., **Smoothing** before sampling.

# Aliasing



aliasing artifacts



anti-aliasing by oversampling

# Temporal Aliasing



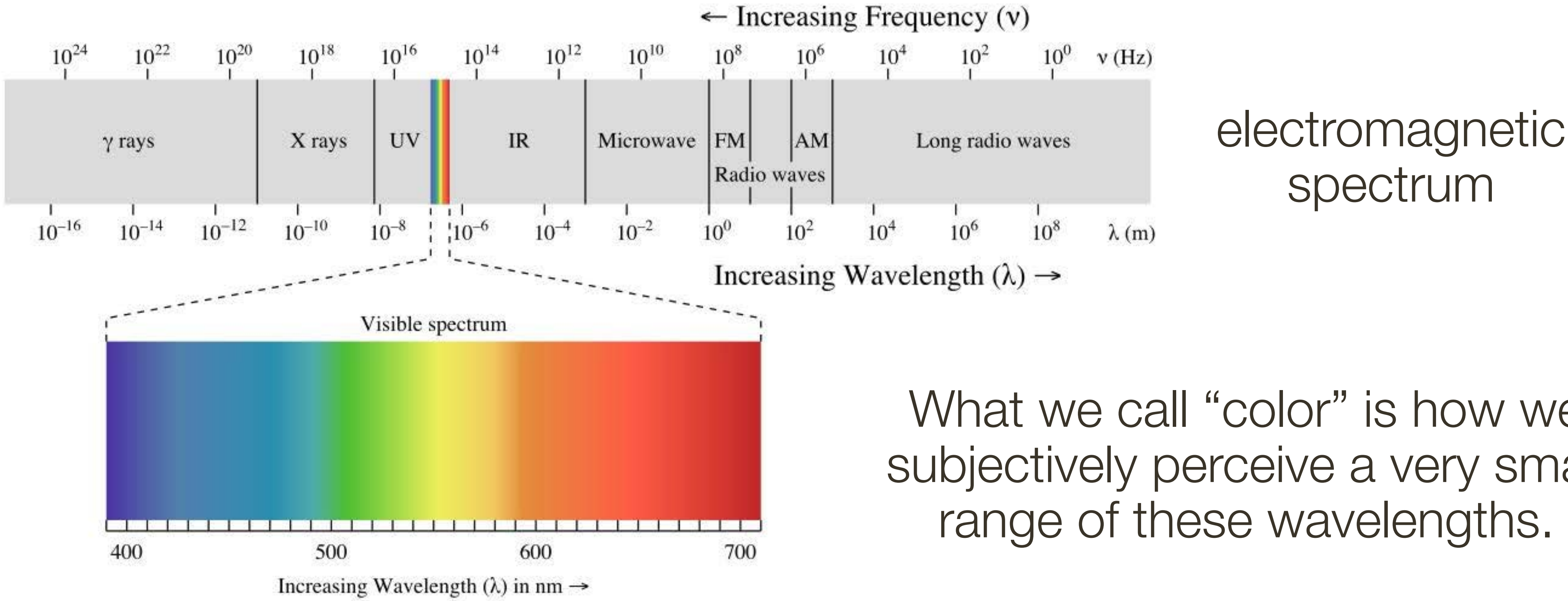
# Temporal Aliasing





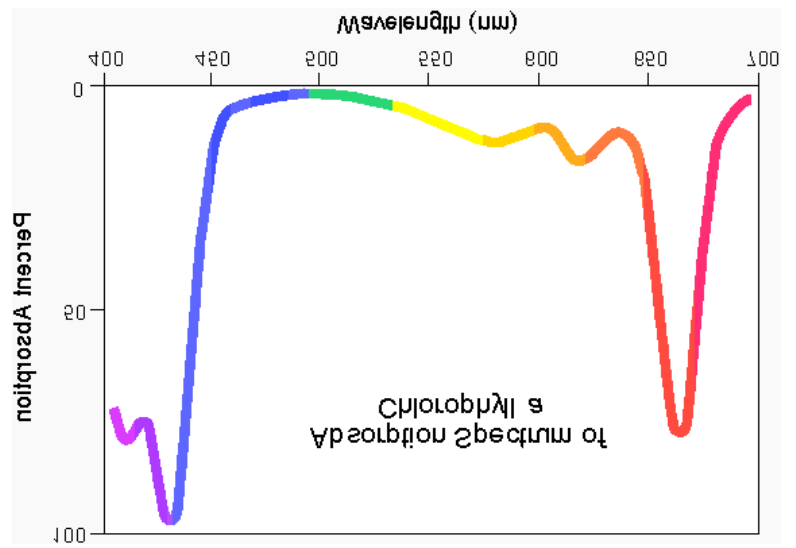
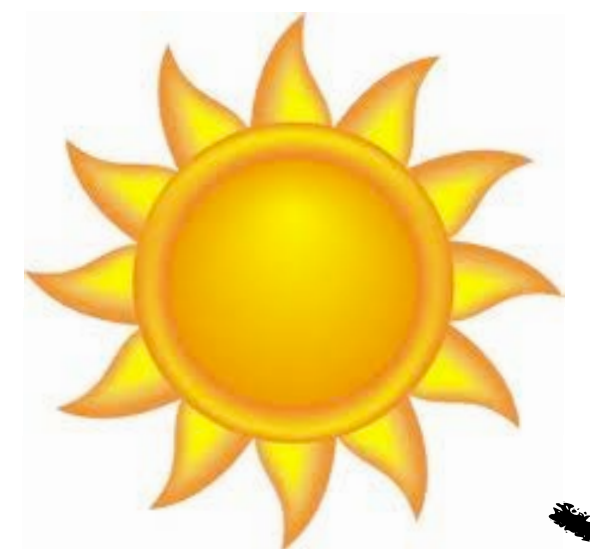
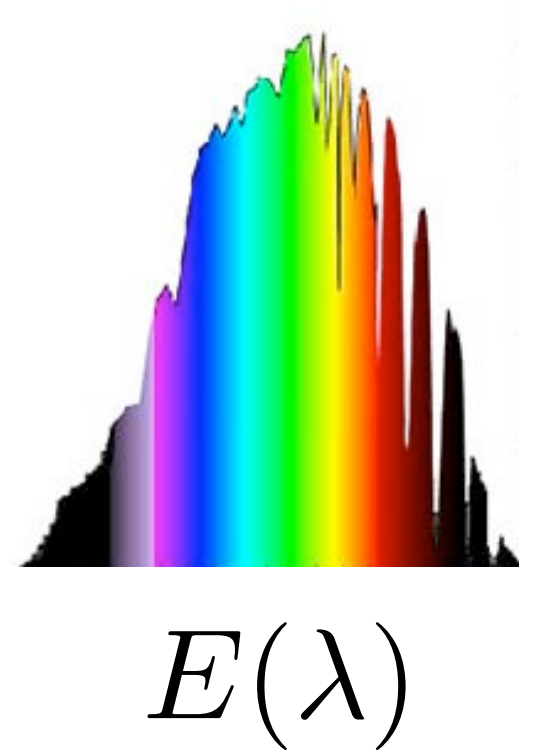
# Color is an Artifact of Human Perception

“Color” is **not** an objective physical property of light (electromagnetic radiation). Instead, light is characterized by its wavelength.



What we call “color” is how we subjectively perceive a very small range of these wavelengths.

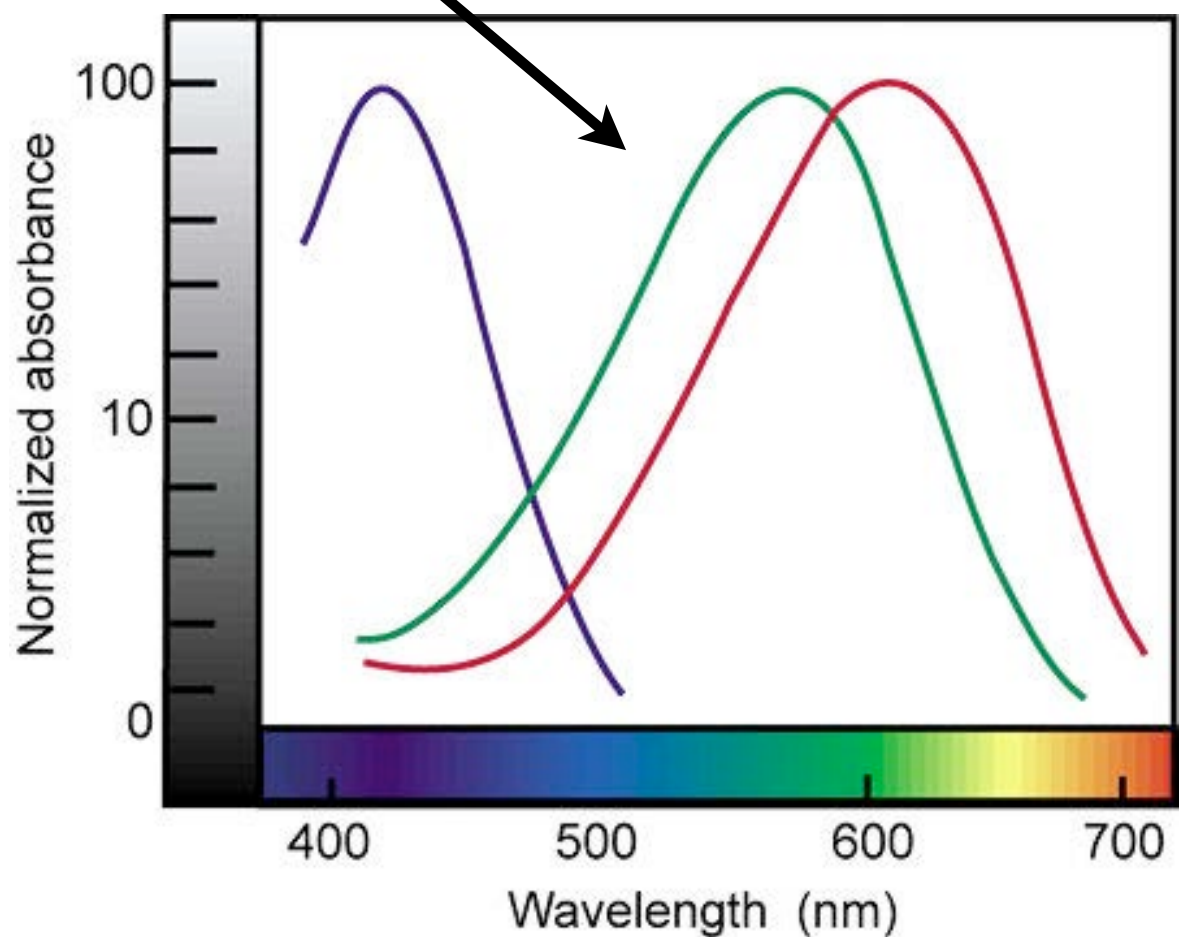
# Colour Perception



Cone responses



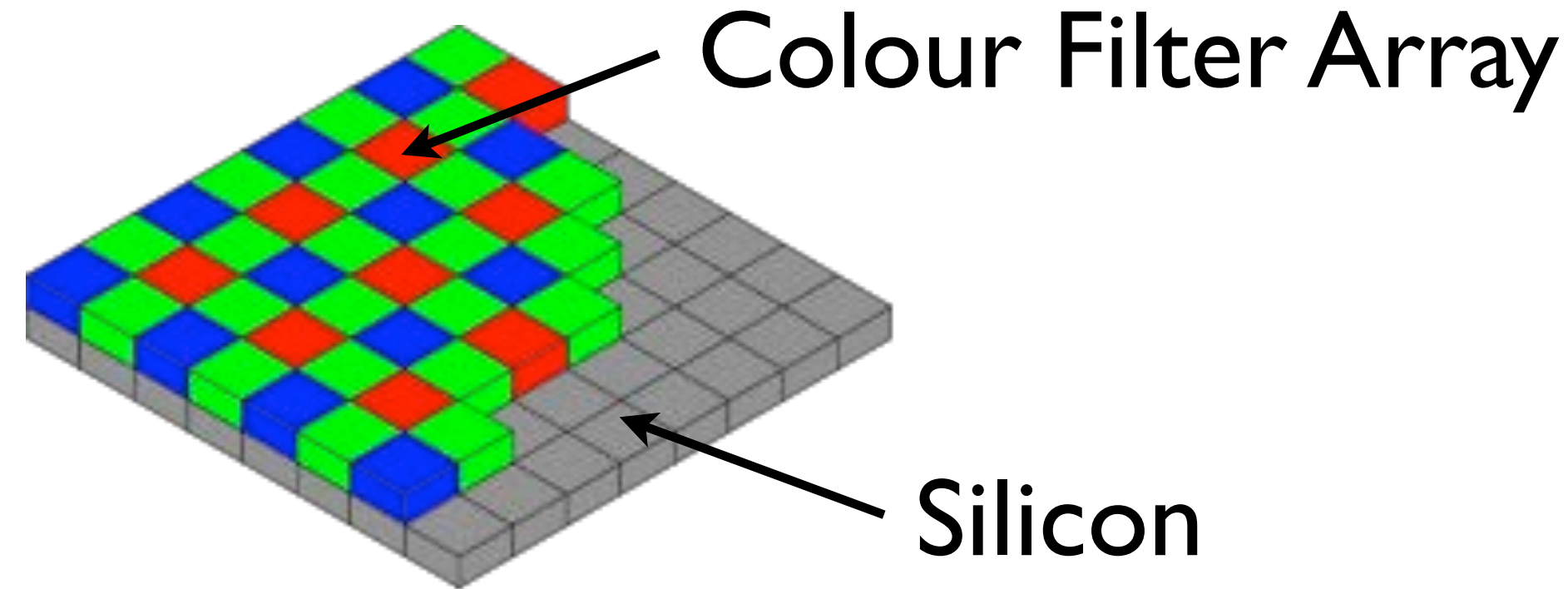
$R_{red}(\lambda)$



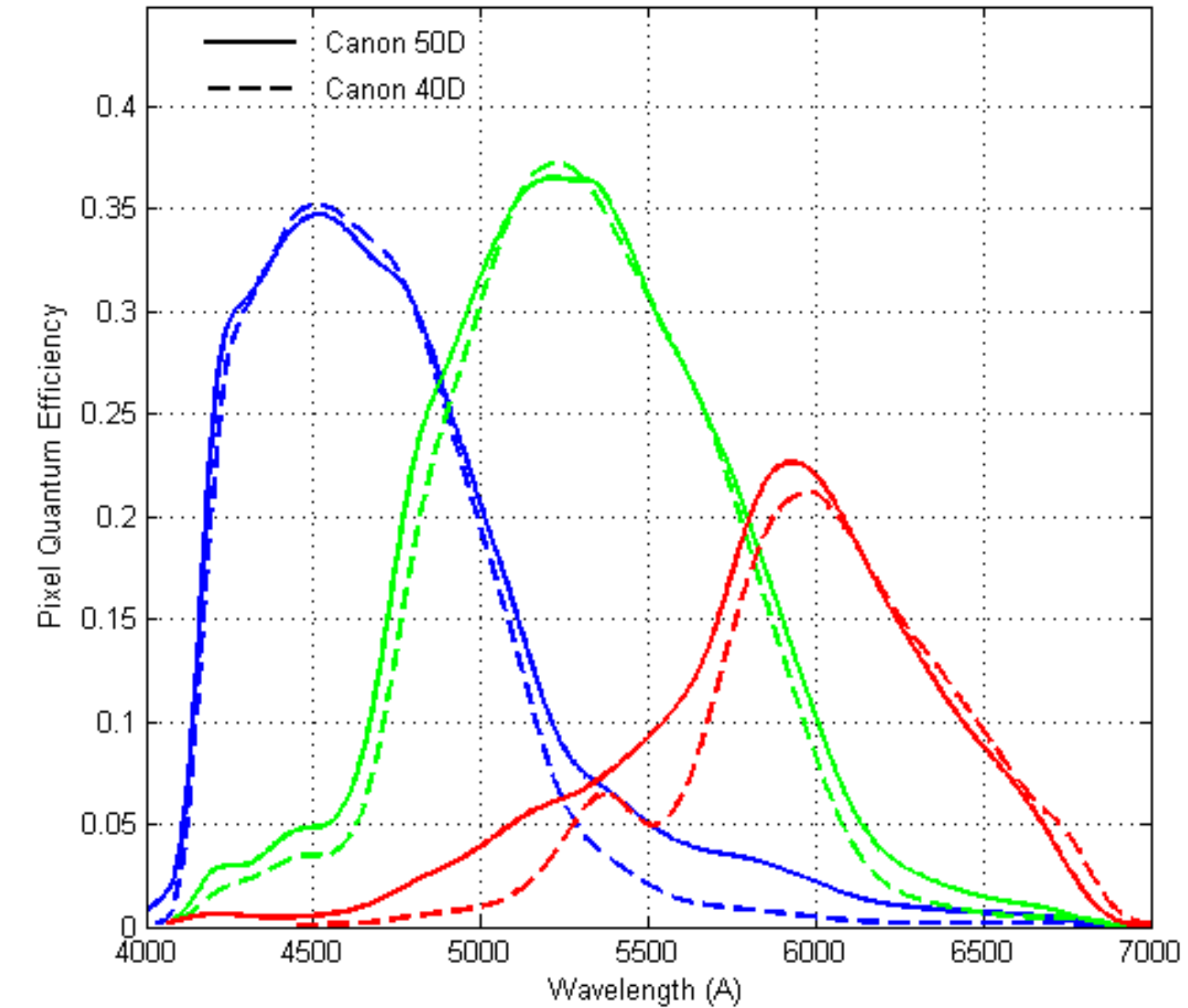
Cone excitation (multiply and add):

$$\rho_{red} = \int R_{red}(\lambda) E(\lambda) S(\lambda) d\lambda$$

# Digital Sensor



Canon 50D

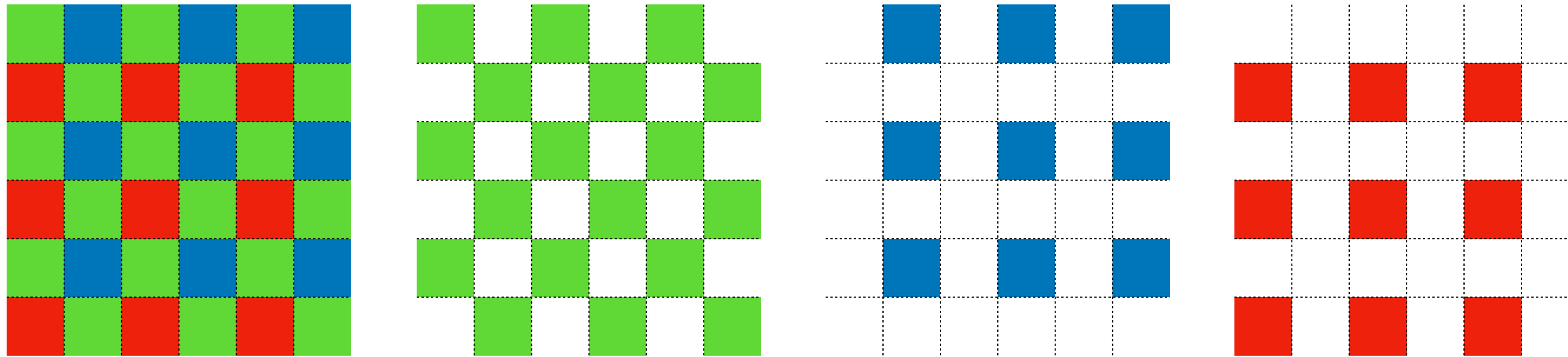


$$f(\lambda)$$

- Analogue image is sampled by a CMOS (or CCD) sensor
- RGB colour filters arranged in a “Bayer” pattern
- Spectral response of R,G,B filters = Quantum Efficiency
- Counts from this sensor are camera RAW

# Demosaicing

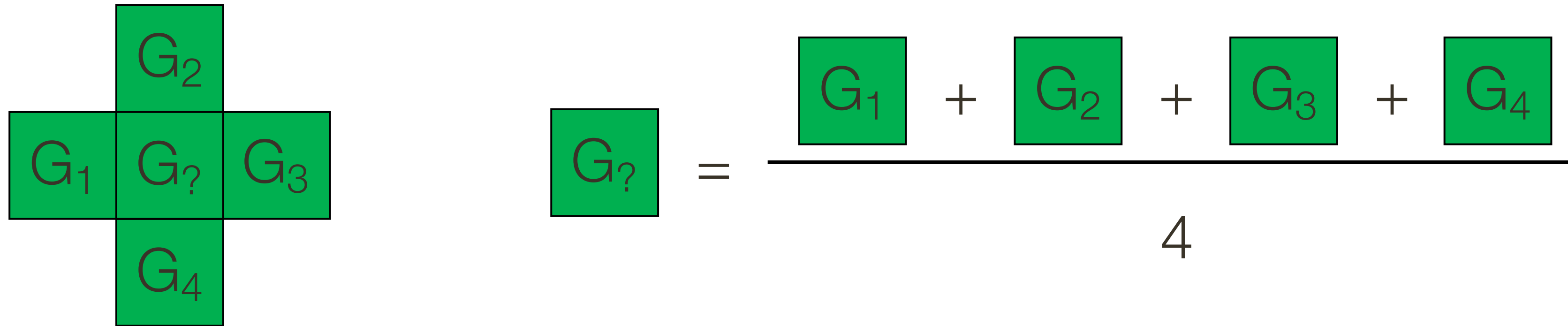
Each colour channel has different information:



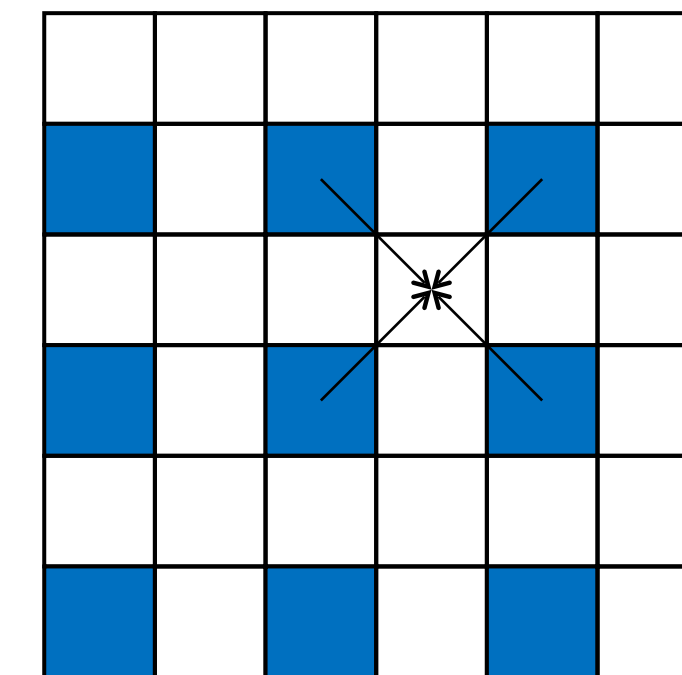
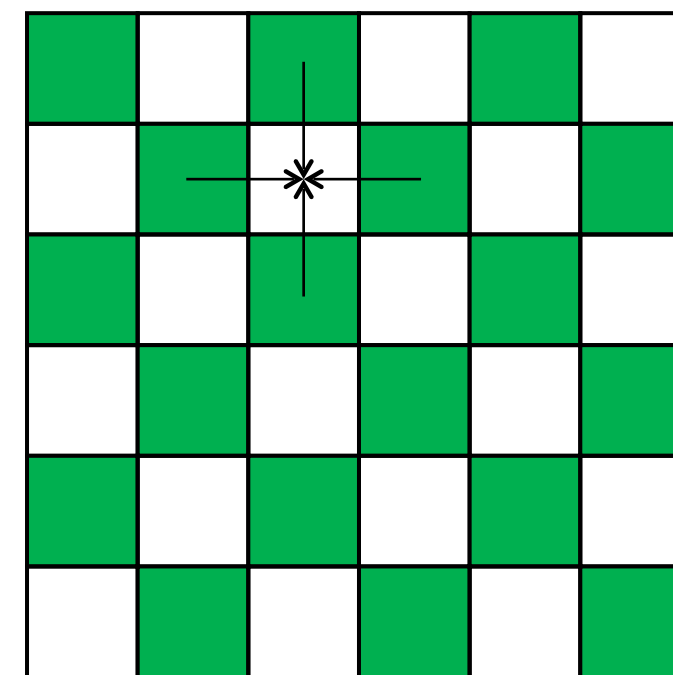
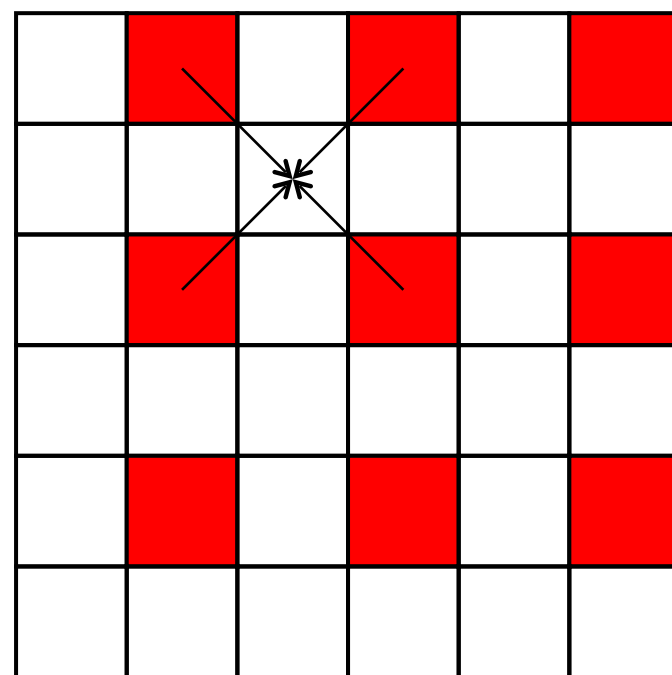
How can we fill in the missing information?

# Demosaicing by Bilinear Interpolation

**Bilinear** interpolation: Simply average your 4 neighbors.



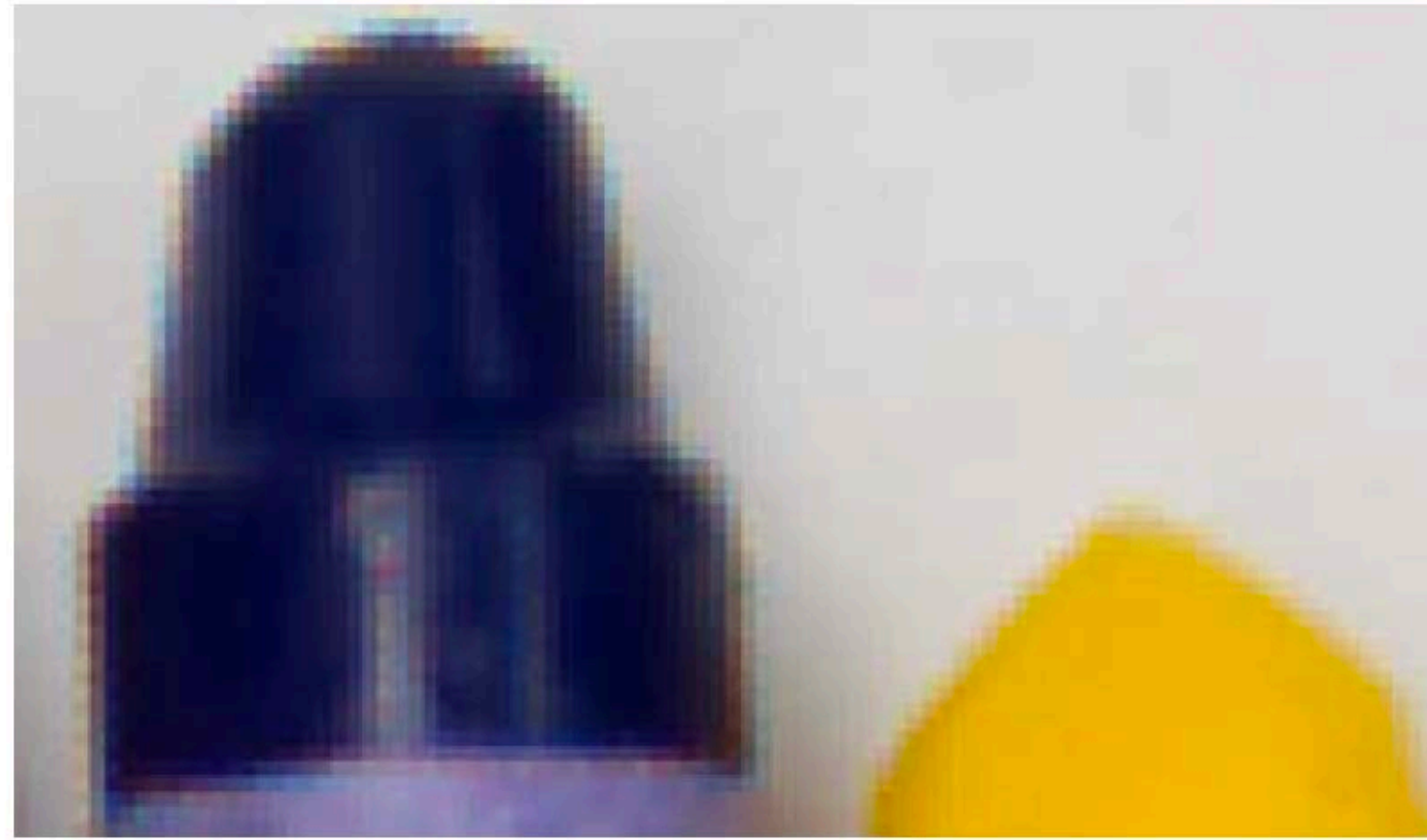
Neighborhood changes for different channels:



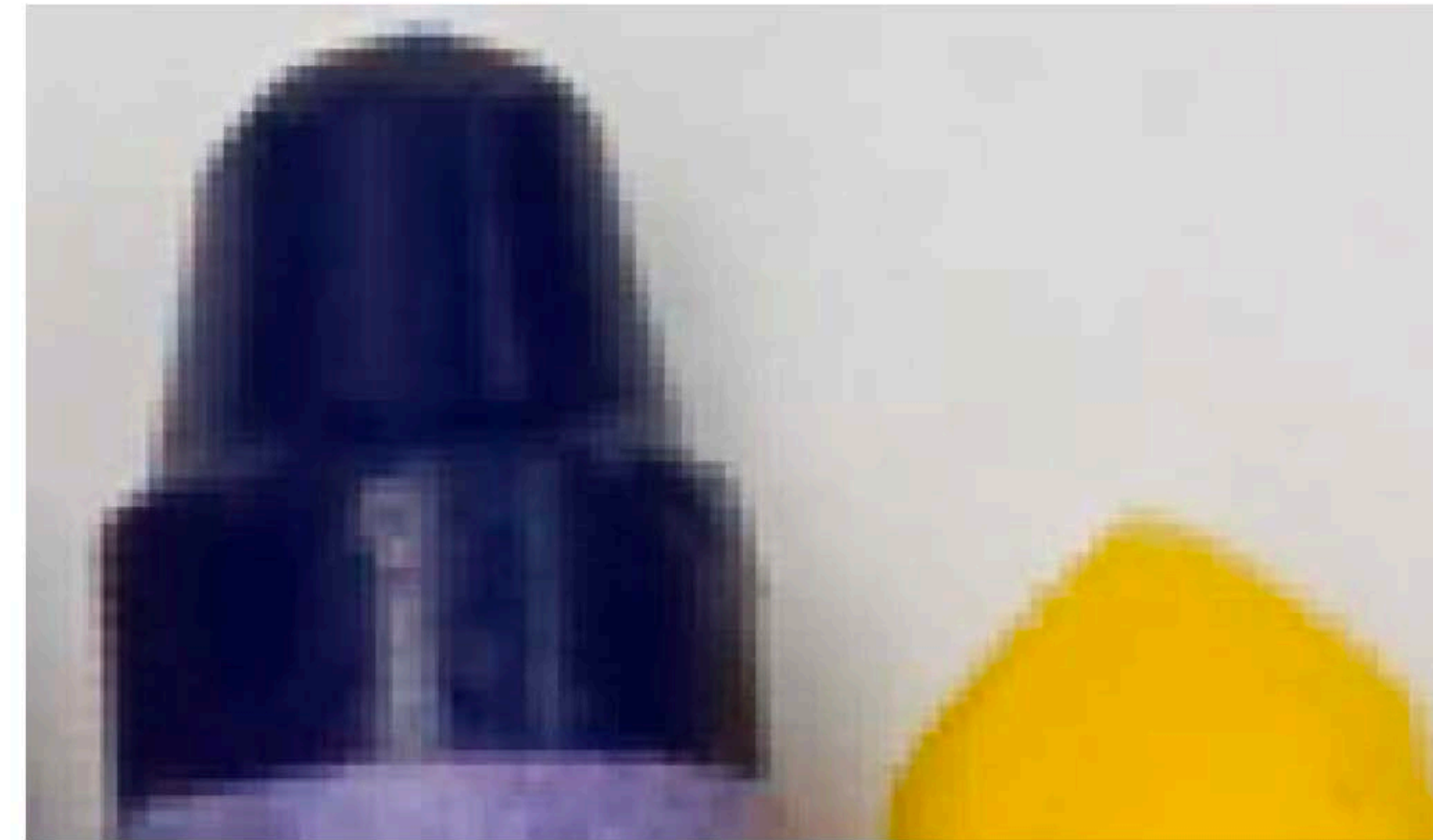
# Demosaicing

Optional subtitle

- Simple interpolation causes colour errors



Bilinear interpolation

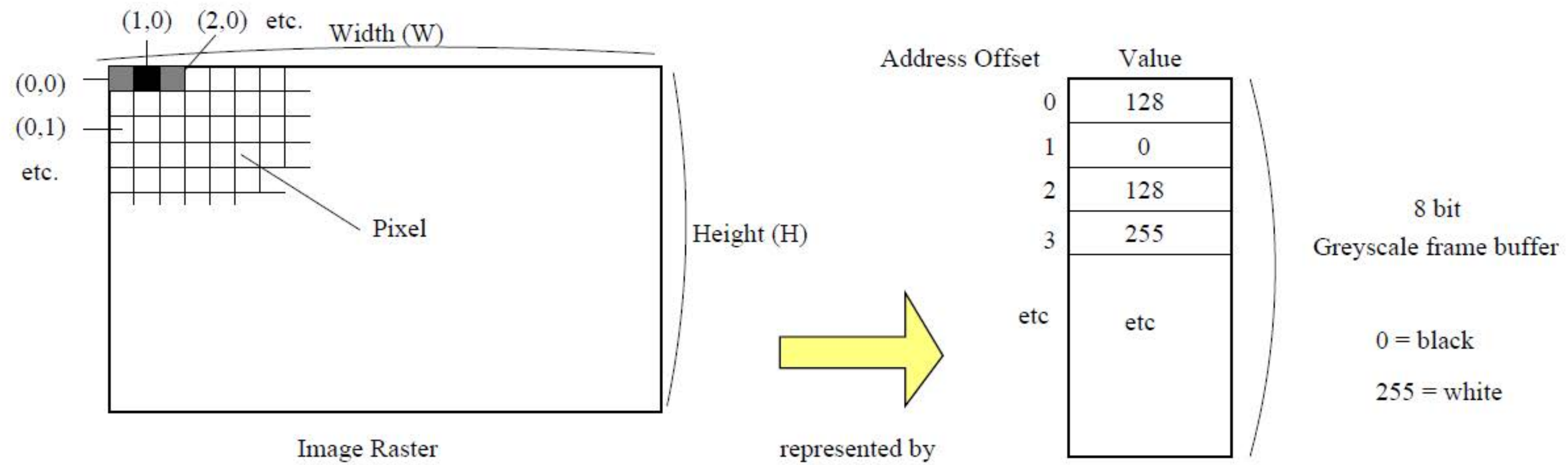


Bennet et al 2006  
(local 2 colour prior)

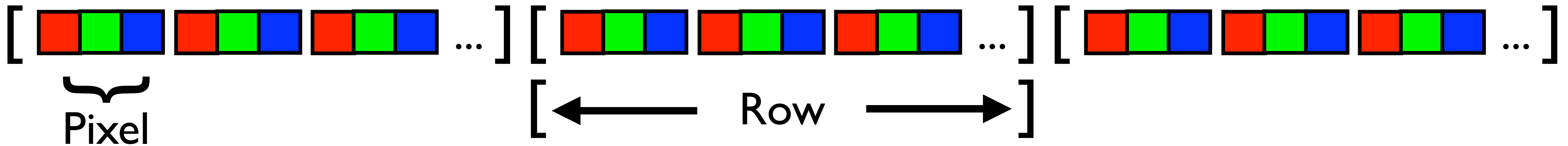
- Many techniques use edge information from the densely sampled green channel, and some form of image prior
- It can also be tackled via a data-driven approach, e.g., [Gharbi et al. 2016]

# The Digital Image

Optional subtitle



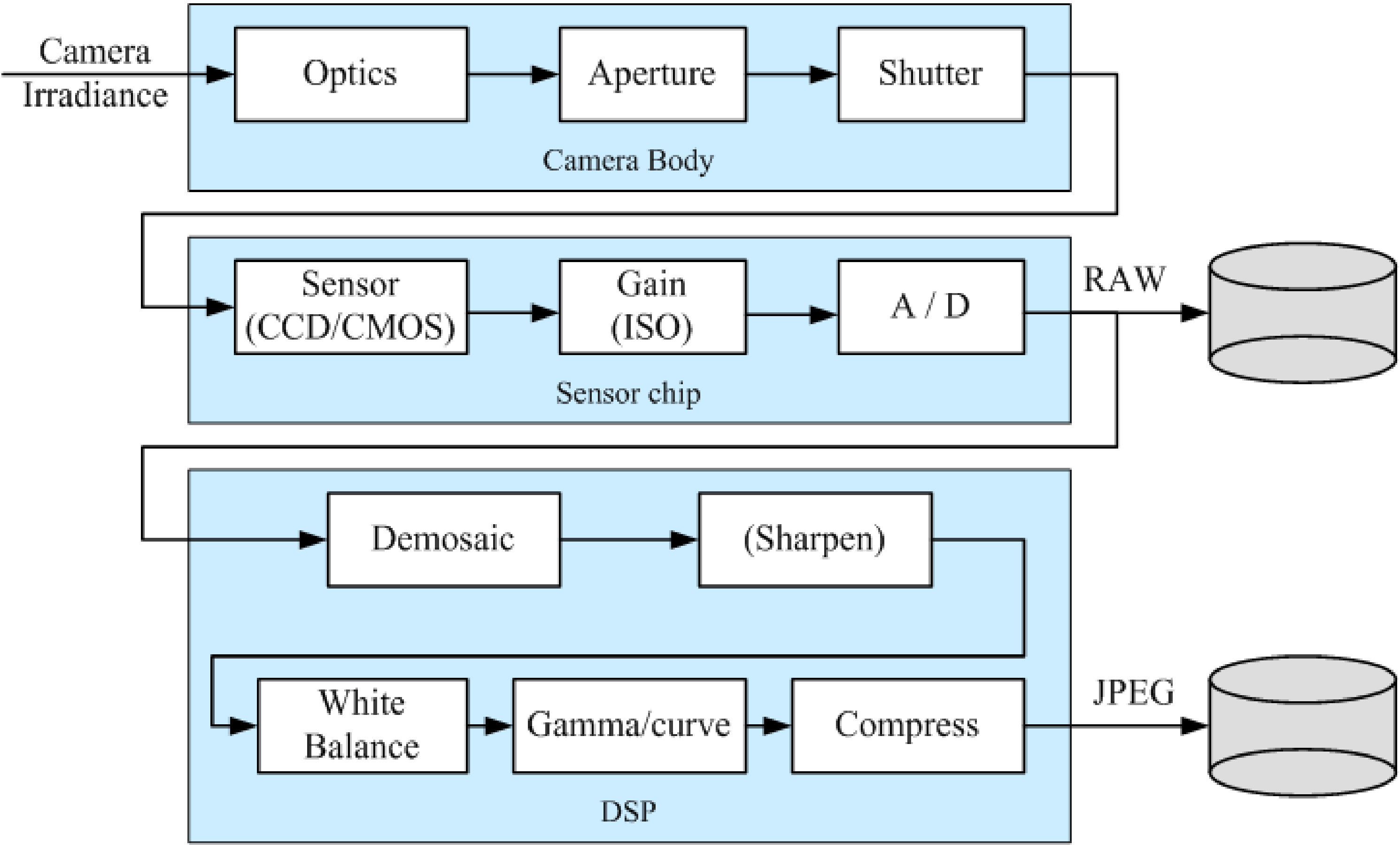
e.g., arranged in memory with RGB pixels stored in rows:



Many other possibilities, e.g., BGR, RGBA pixels, row/column major ordering, and rows or columns aligned to power of 2 boundaries

# Digital Camera Processing

Main stages in a digital camera









# White Balance

Optional subtitle

- Humans are good at adapting to global illumination conditions: you would still describe a white object as white whether under blue sky or candle light.
- However, when the picture is viewed later, the viewer is no longer correcting for the environment and the illuminant colour typically appears too strong.
- **White balancing** is the process of correcting for the illuminant



- A simple white balance algorithm is to assume the scene is grey on average “greyworld”, state of the art methods use learning, e.g., Barron ICCV 2015

# Gamma Correction

Optional subtitle

- Equal steps in luminance  $\neq$  equal in perceived brightness

linear luminance (raw) 

0.0	0.1	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9	1.0
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equal brightness steps 

0.0	0.1	0.2	0.3	0.4	0.5	0.6	0.7	0.8	0.9	1.0
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- Equal steps in human perceived brightness are achieved by increasingly large steps in luminance (sensor counts)
- So we encode pixel values  $V$  using a power law:



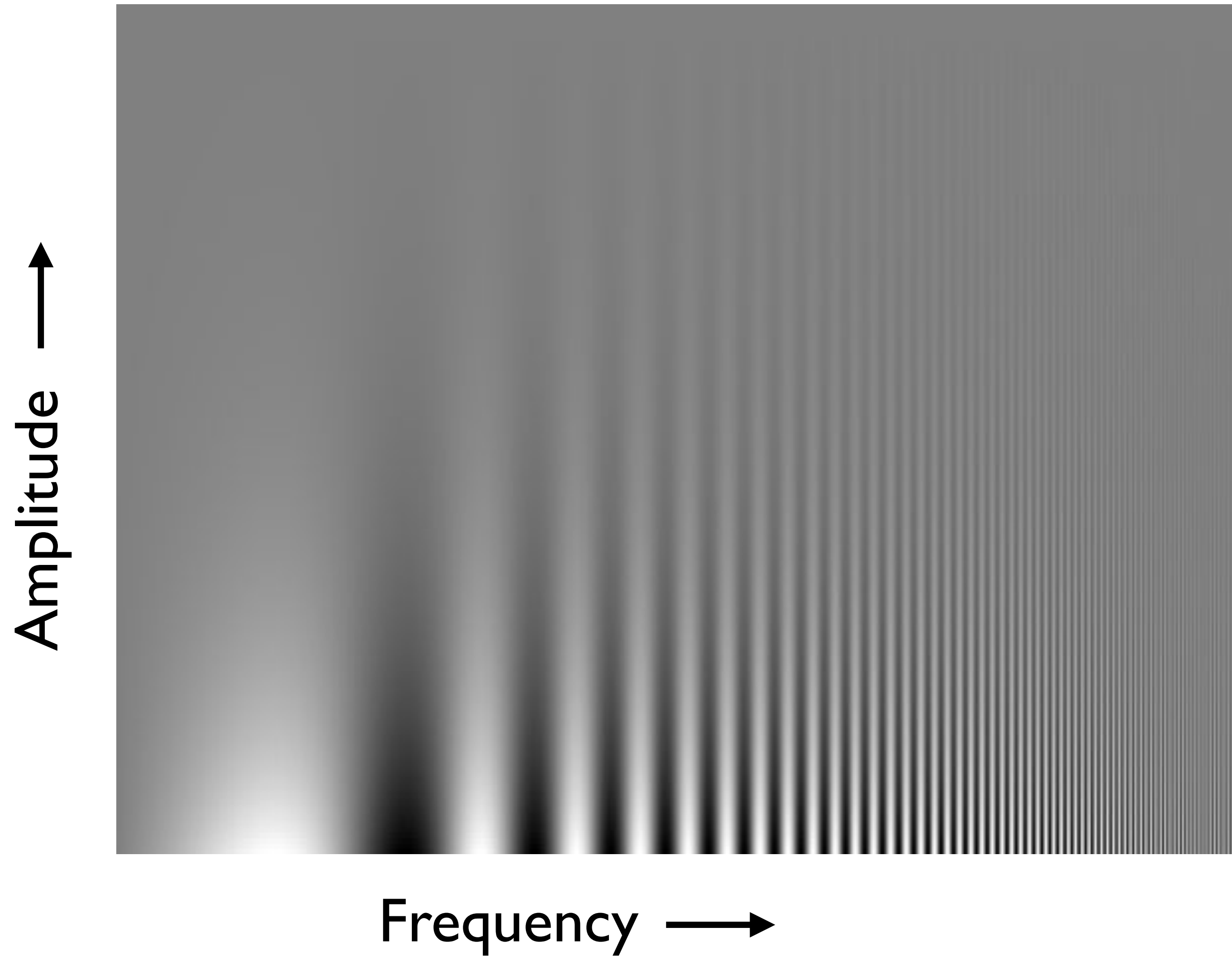
$$L = V^\gamma$$

- Using raw sensor counts wastes bits as we can't differentiate the large values  
→ use **gamma corrected encoding (V)** that allocates more bits to smaller

# Contrast Sensitivity

Optional subtitle

Human visual system is most sensitive to mid-frequencies



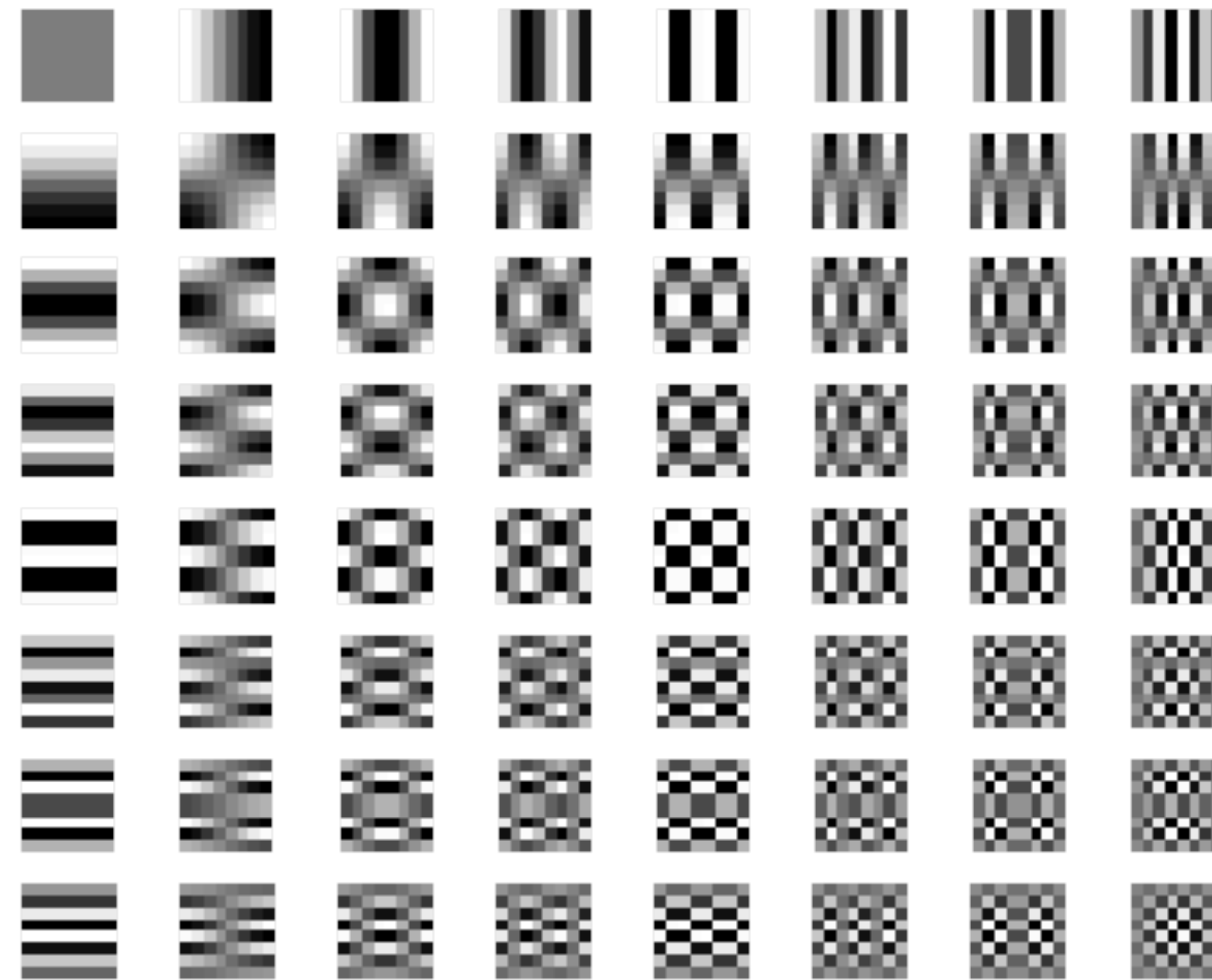
# Discrete Cosine Transform

Optional subtitle

- Basis functions used in JPEG

$$X(m, n) = \alpha_m \alpha_n \sum_{k=0}^{K-1} \sum_{l=0}^{L-1} x(k, l) \cos \left[ \frac{(2k+1)m\pi}{2K} \right] \cos \left[ \frac{(2l+1)n\pi}{2L} \right]$$

- Energy is concentrated in the low-frequency components
- Efficient algorithm to compute (similar to FFT)



8x8 basis functions

# Summary

In the continuous case, images are functions of two spatial variables,  $x$  and  $y$ .

The discrete case is obtained from the continuous case via sampling (i.e. tessellation, quantization).

If a signal is **bandlimited** then it is possible to design a sampling strategy such that the sampled signal captures the underlying continuous signal exactly (**Nyquist Sampling**).

Human **trichromatic colour** perception, and other perceptual sensitivities such as contrast sensitivity influence the image coding pipeline.