

#### THE UNIVERSITY OF BRITISH COLUMBIA

**Lecture 3:** Image Formation (continued)

# **CPSC 425: Computer Vision**



( unless otherwise stated slides are taken or adopted from **Bob Woodham, Jim Little** and **Fred Tung** )

## **Menu** for Today (**September 11, 2024**)

### **Readings:**

- **Today's** Lecture: Forsyth & Ponce (2nd ed.) 4.1, 4.5
- **Next** Lecture: none

#### **Reminders:**

— Complete **Assignment 0** (ungraded) by Wednsday, **September 11** — **Assignment 1** (graded) is out Wednsday, **September 11**



## **Topics:**

#### — **Lenses**

— Human **eye** (as a camera)

## — Image as a **function** — **Linear filtering**



## Today's "fun" Example #1: Nudging



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#### Aerial view of the white stripes at the lake shore drive in Chicago.

## Today's "fun" Example #1: Anchoring and Ordering

#### Champagne



#### Sparkling Wines



#### Rose Wines



#### Sweet Wines



#### Champagne, Sparkling, Rose, Sweet Wines



Developed by the French company **Varioptic**, the lenses consist of an oilbased and a water-based fluid sandwiched between glass discs. Electric charge causes the boundary between oil and water to change shape, altering the lens geometry and therefore the lens focal length

The intended applications are: auto-focus and image stabilization. No moving parts. Fast response. Minimal power consumption.



Video Source: https://www.youtube.com/watch?v=2c6ICdDFOY8

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### **Electrostatic** field between the column of water and the electron (other side of power supply attached to the pipe) - see full video for complete explanation



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add auto-focus capability to it DataMan line of industrial ID readers (press release May 29, 2012)



# As one example, in 2010, **Cognex** signed a license agreement with Varioptic to

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### Surface reflection depends on both the **viewing**  $(\theta_v, \phi_v)$  and **illumination**  $(\theta_i, \phi_i)$ direction, with Bidirectional Reflection Distribution Function:  $\mathbf{BRDF}(\theta_i, \phi_i, \theta_v, \phi_v)$

**Slide adopted from**: Ioannis (Yannis) Gkioulekas (CMU)





 $\textbf{BRDF}(\theta_i, \phi_i, \theta_v, \phi_v) = \frac{\rho_d}{\sigma}$  $\pi$ **Lambertian** surface:

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(✓*i, i*)(✓*r, r*) the light and the surface (geometry)  $(\vec{i} \cdot$ **To sum up**: For a perfect **lambertian** surface reflected light is (1) amount and color of incident light  $-1$  (2) fraction of light being reflected (material) — (2) fraction of light being reflected (material)  $-\rho_d$ <br>(3) angle between the light and the surface (geometry)  $-$ ⇡*L* = ⇢*d* ⇡  $\overline{\sqrt{i}}$  $i \cdot \vec{n}$ ⇢*d*  $\dot{t}$ *I*(~ *i ·*



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**Mirror** surface: all incident light reflected in one directions  $(\theta_v, \phi_v) = (\theta_r, \phi_r)$ 

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## Lecture 2: Re-cap Pinhole Camera Abstraction

#### **Pinhole** Camera Abstraction



$$
x' = f' \frac{x}{z}
$$
  
\n
$$
y' = f' \frac{y}{z}
$$
  
\n
$$
x' = mx \t m = \frac{f'}{z_0}
$$
  
\n
$$
x' = x
$$
  
\n
$$
y' = y
$$

to 2D image point 
$$
P' = \begin{bmatrix} x' \\ y' \end{bmatrix}
$$
 where

#### **Lecture 2**: Re-cap Projection  $P =$  $\sqrt{2}$ 4 *x y z*  $\overline{1}$ *proje*  $rac{1}{2}$ 3D object point  $P = |y|$  projects to 2D image point  $P' = |y|$ , where

## Perspective

### Weak Perspective

Orthographic

## **Lecture 2**: Re-cap Reason for Lenses



A real camera must have a finite aperture to get enough light, but this causes

**Solution**: use a **lens** to focus light onto the image plane

# blur in the image

## Lecture 2: Re-cap Thin Lens Equation



### Forsyth & Ponce (1st ed.) Figure 1.9





## Lecture 2: Re-cap Thin Lens Equation

#### **Focal Length:** Property of the lens (geometry and refraction index)



### Forsyth & Ponce (1st ed.) Figure 1.9





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## **Lecture 2**: Re-cap Thin Lens Equation

#### **Focal Length**: Property of the lens (geometry and refraction index)



Depth of the point (P) in the world







### Forsyth & Ponce (1st ed.) Figure 1.9

## **Lecture 2**: Re-cap Thin Lens Equation

#### **Focal Length**: Property of the lens (geometry and refraction index)



imaging plane where the projection of this point (P) will be in focus

$$
\frac{1}{z'}-\frac{1}{z}
$$

# Depth of the point





## **Pinhole Camera with a Lens**

**Perspective Projection:** location in the image where a 3D world point projects

 $\mathbf{V}'$ 

 $\gamma$ 

 $X'$ 

Thin Lens Equation: depth of the imaging plane itself where this point will be in focus

$$
= f' \frac{x}{z}
$$

$$
= f' \frac{y}{z}
$$

$$
-\frac{1}{z}=\frac{1}{f}
$$

## Lens Basics

A lens focuses parallel rays (from points at infinity) at focal length of the lens Rays passing through the center of the lens are not bent



## **Lens Basics**



Objects off the plane are blurred depending on the distance



## **Perspective** Projection + Thin Lens Examples

Where would the focusing plane be for various positions of the object?

 $1 \quad 1 \quad 1$  $\frac{1}{z'} - \frac{1}{z} = \frac{1}{f}$ 

https://www.physicsclassroom.com/class/refrn/Lesson-5/Converging-Lenses-Object-Image-Relations

 $\frac{1}{z'} - \frac{1}{z}$ = 1 *f*

## **Perspective** Projection + **Thin Lens** Examples



Where would the focusing plane be for various positions of the object?

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 $\frac{1}{z'} - \frac{1}{z}$ = 1





### Objects **further** away than the **focal length**

Where would the focusing plane be for various positions of the object?

 $\frac{1}{z'} - \frac{1}{z}$ = 1



### Objects **further** away than the **focal length**



Where would the focusing plane be for various positions of the object?



### Objects at 2 x **focal length**

Where would the focusing plane be for various positions of the object?





### Objects at 2 x **focal length**

Where would the focusing plane be for various positions of the object?

 $\frac{1}{z'} - \frac{1}{z}$ = 1



### Objects at the **focal length**

Where would the focusing plane be for various positions of the object?



### Objects **closer** than the **focal length**

Where would the focusing plane be for various positions of the object?





### Objects **closer** than the **focal length**





Where would the focusing plane be for various positions of the object?





Smaller aperture  $\Rightarrow$  smaller blur, larger depth of field

## Depth of Field



#### Aperture size =  $f/N$ ,  $\Rightarrow$  large N = small aperture



## **Real** Lenses



- Real Lenses have multiple stages of positive and negative elements with differing refractive indices
- This can help deal with issues such as chromatic aberration (different colours bent by different amounts), vignetting (light fall off at image edge) and sharp imaging across the zoom range

## **Spherical Aberration**



#### Forsyth & Ponce (1st ed.) Figure 1.12a

## **Spherical Aberration**

#### Un-aberrated image



#### Image from lens with Spherical Aberration



## Compound Lens Systems





### A modern camera lens may contain multiple components, including aspherical elements

## Vignetting

### Vignetting in a two-lens system



### Forsyth & Ponce (2nd ed.) Figure 1.12

The shaded part of the beam never reaches the second lens

## Vignetting



Image Credit: Cambridge in Colour

## Chromatic **Aberration**

- Index of **refraction depends on wavelength**, λ, of light
- Light of different colours follows different paths
- Therefore, not all colours can be in equal focus





**Image Credit: Trevor Darrell** 



# Other (Possibly Significant) **Lens Effects**

- Chromatic **aberration**
- $-$  Index of refraction depends on wavelength, λ, of light
- Light of different colours follows different paths
- Therefore, not all colours can be in equal focus
- **Scattering** at the lens surface
- Some light is reflected at each lens surface
- There are other **geometric phenomena/distortions**
- pincushion distortion
- barrel distortion
- etc

## Lens **Distortion**





#### Fish-eye Lens



- Szeliski (1st ed.) Figure 2.13
- Lines in the world are no longer lines on the image, they are curves!



## **Human** Eye

- The eye has an **iris** (like a camera)
- **Focusing** is done by changing shape of lens
- When the eye is properly focused, light from an object outside the eye is imaged on the **retina**
- The retina contains light receptors called **rods** and **cones**



### **pupil** = pinhole / aperture

### **retina** = film / digital sensor

**Slide adopted from: Steve Seitz** 

## Fun **Aside**





https://io9.gizmodo.com/does-your-brain-really-have-the-power-to-see-the-world-5905180



#### **George M. Stratton**



## **Human** Eye

### **pupil** = pinhole / aperture

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## Two-types of **Light Sensitive Receptors**

#### **Cones**

 6-7 million cone-shaped receptors color vision operate in high light less sensitive yield higher resolution

- 
- 



**Slide adopted from: James Hays** 

#### **Rods**

 75-150 million rod-shaped receptors **not** involved in color vision, gray-scale vision only operate at night highly sensitive, can responding to a single photon yield relatively poor spatial detail

## Human Eye



**Slide adopted from: James Hays** 



### **Density** of rods and cones

## Lecture **Summary**

— We discussed a "physics-based" approach to image formation. Basic abstraction is the **pinhole camera**.

— **Lenses overcome limitations** of the pinhole model while trying to preserve it as a useful abstraction

- Projection equations: **perspective**, weak perspective, orthographic
- Thin lens equation
- Some "aberrations and **distortions**" persist (e.g. spherical aberration, vignetting)
- The **human eye** functions much like a camera

